

Correlations between microstructure and rheological behaviour of partial melt alloys

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Outline

- Introduction
- Phenomenology of the behaviour of globular structures
- Phenomenology of the behaviour of dendritic structures
- Modelling
- Conclusion

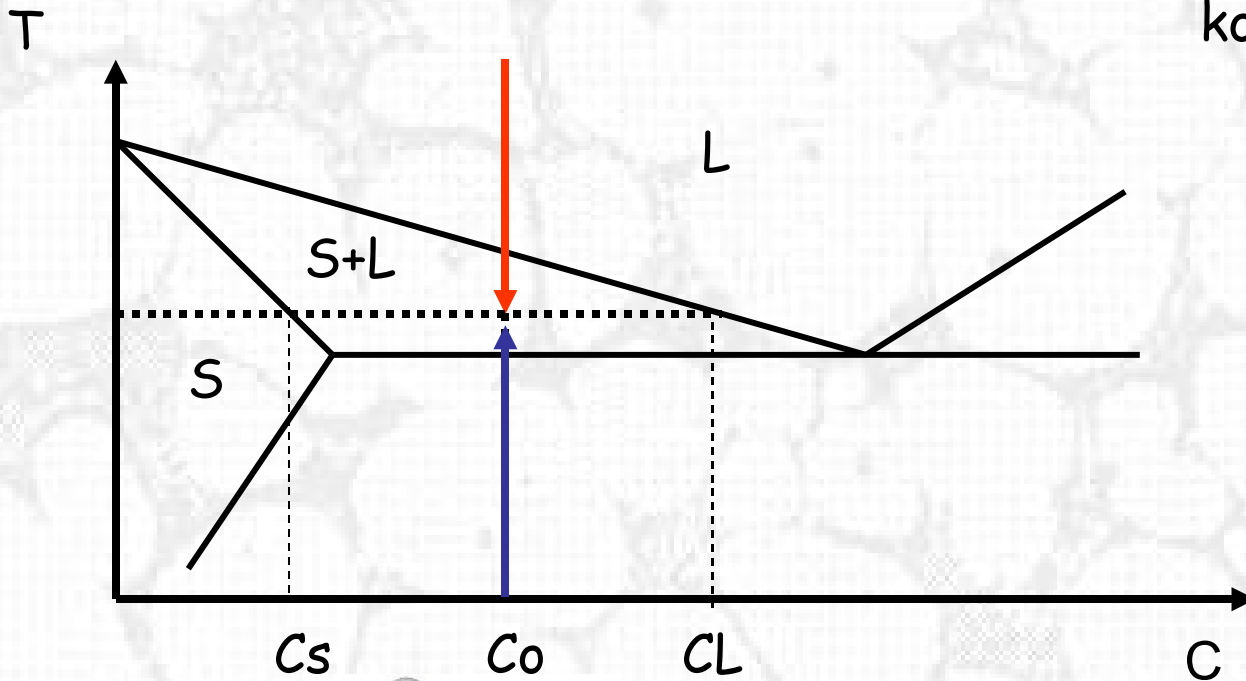
Introduction

Partial melts in alloys

➡ **During solidification**

➡ **During partial melting**

Partition ratio
 $k_0 = C_s / C_L$



Main parameter = volume fraction of solid f_s

☞ **Equilibrium: lever rule**

$$f_s = (C_L - C_0) / (C_L - C_s)$$

☞ **No solid diffusion: Scheil equation**

$$C_s = k_0 \cdot C_0 (1 - f_s)^{(k_0 - 1)}$$

Other parameters for the solid

Size

Morphology

Solid-liquid interface area

Connectivity of the solid particles

...

Generally

For semi-solid alloys at **low solid fractions** (suspensions),

shear viscosity is used to characterise the behaviour which is assumed to be homogeneous (no phase separation)

Viscosity = F (liquid viscosity, shear rate, time, solid characteristics)

Higher solid fractions

segregation phenomena can occur



Two-phase viscoplastic models

Very high solid fractions

No liquid flow



Porous solid with liquid pockets or films

Two main situations:

Forming in the semi-solid state \Rightarrow $\left\{ \begin{array}{l} - \text{globular structures} \\ - 0.2 < f_s < 0.6 \end{array} \right.$

- ☞ Suspension models usually sufficient
- ☞ Two-phase models at high solid fractions for prediction of phase separation (sponge effect)

Conventional solidification \Rightarrow $\left\{ \begin{array}{l} - \text{dendritic structures} \\ - 0 < f_s < 1 \end{array} \right.$

- ☞ Suspension models are of no use
- ☞ Two-phase models are required for prediction of defects (segregation, pores, hot tears...)

Phenomenology of the behaviour of globular structures

Effect of solid fraction

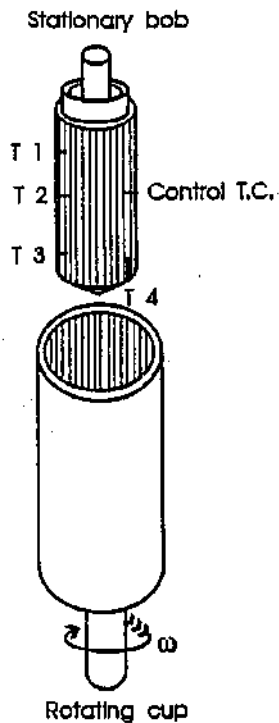
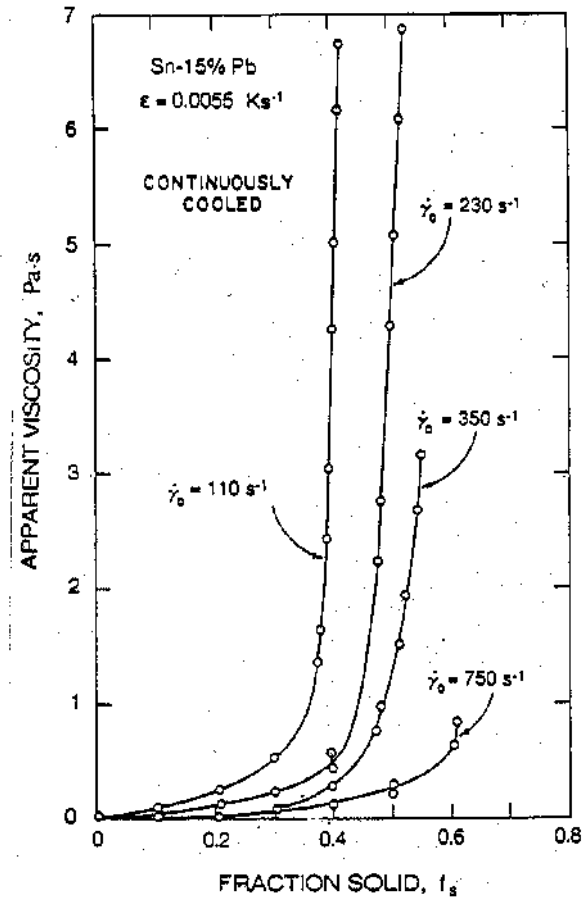


Figure 3: Schematic of graphite rotating cup and stationary bob.



Effect of shear rate: shear thinning behaviour

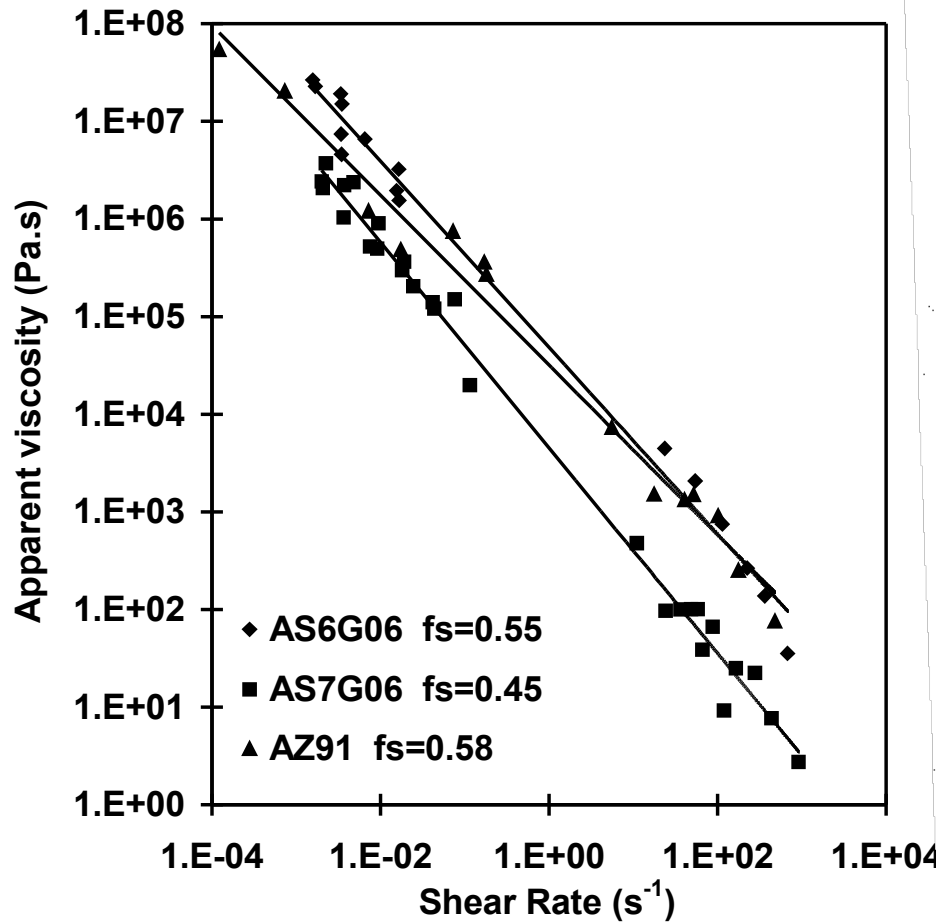
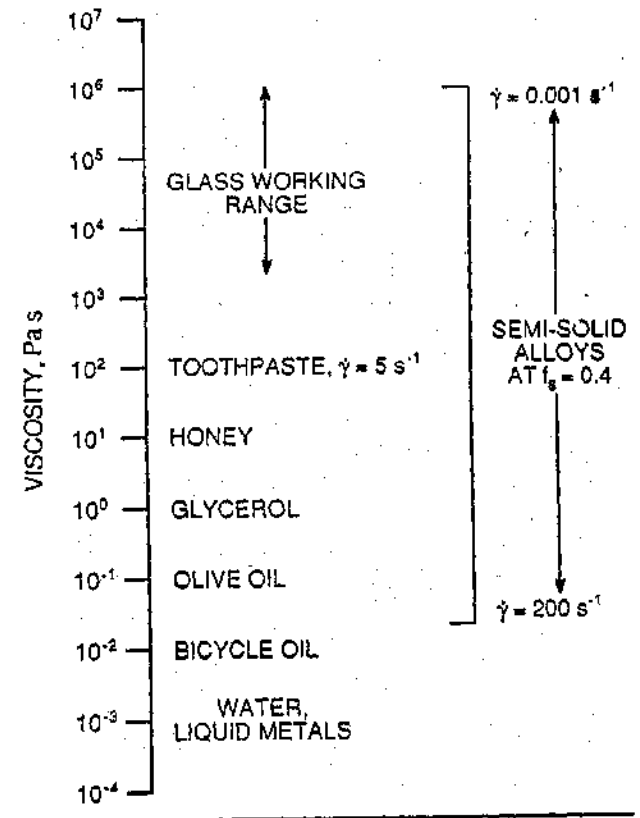
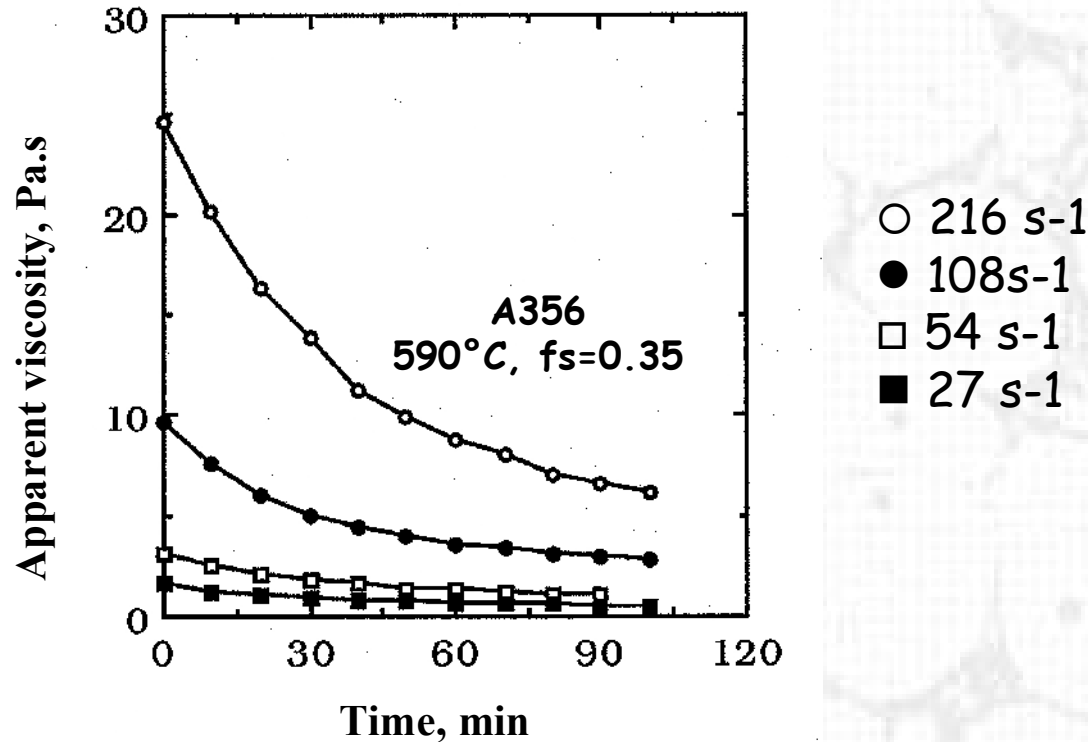


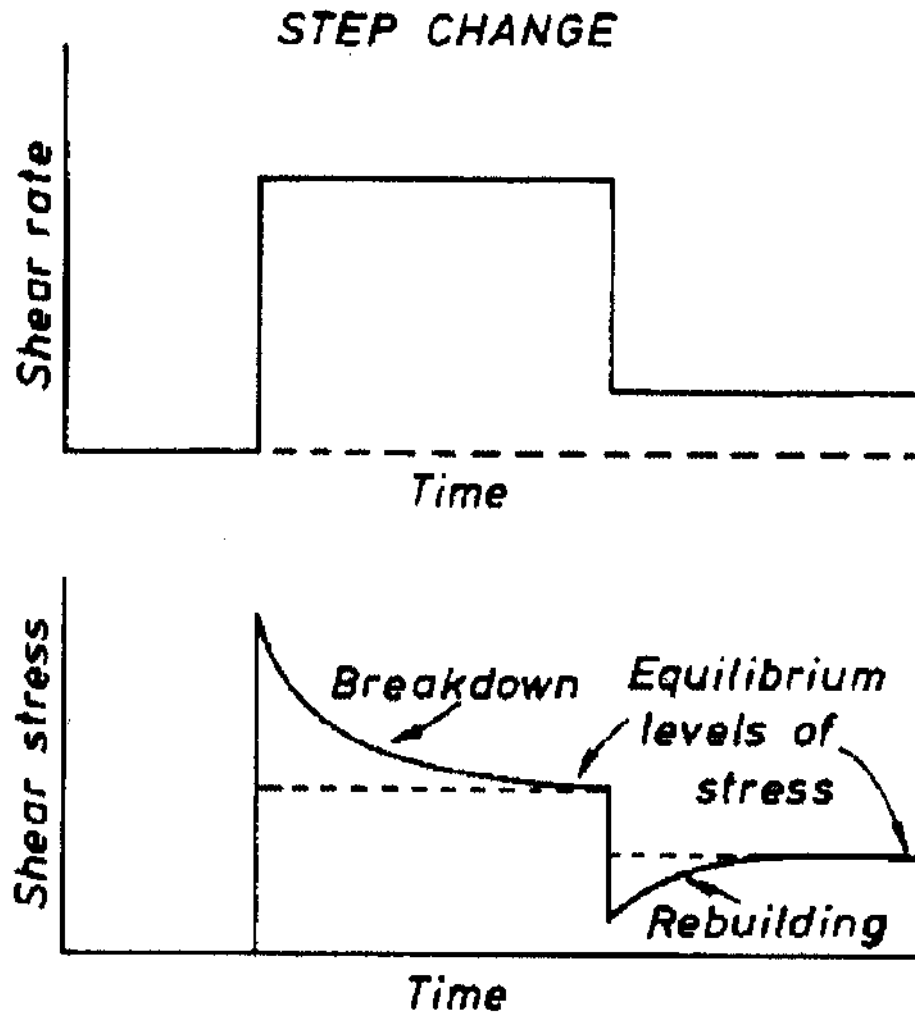
Table I. Some Typical Viscosities

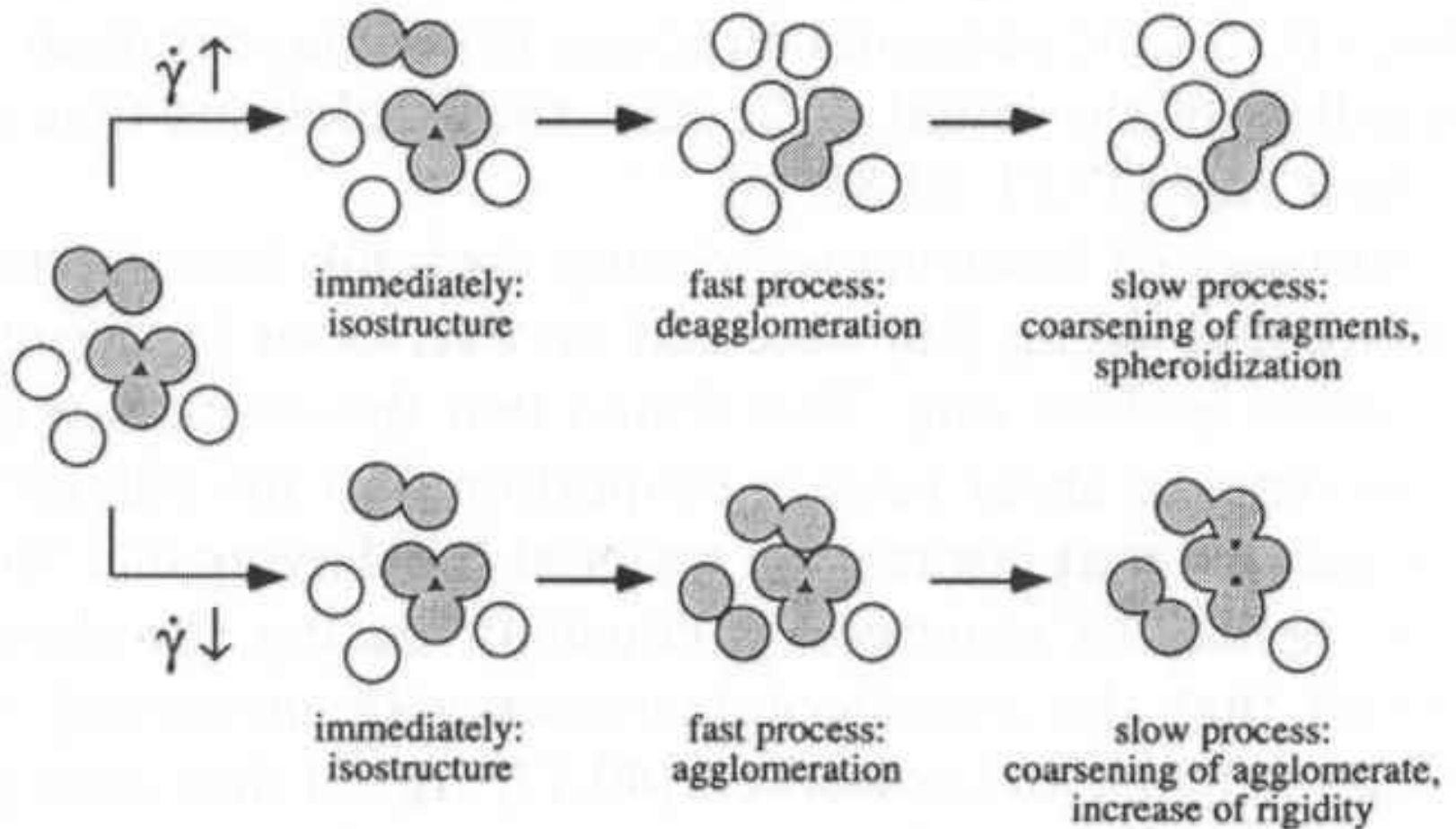


In addition, strong influence of time on viscosity (or shear stress)

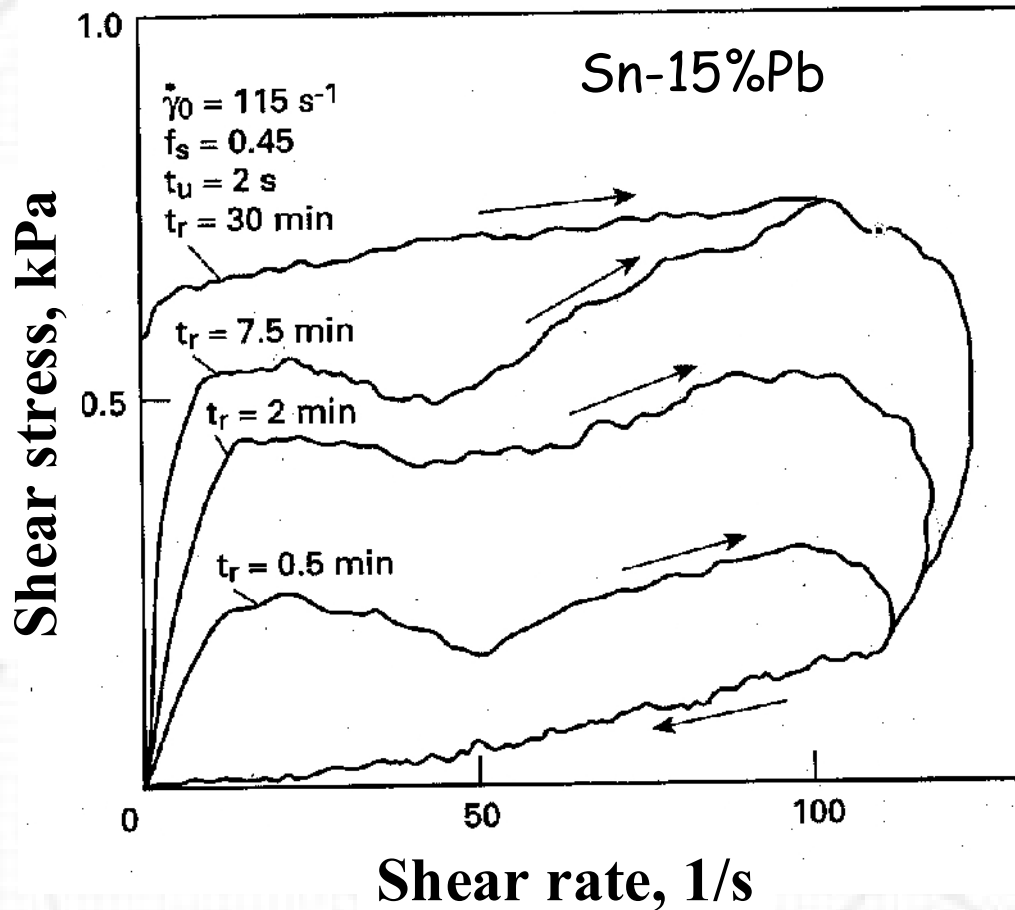


= **thixotropy** interpreted by agglomeration and deagglomeration phenomena of globules which depend on time and shear rate





Effect of rest time



t_r = rest time

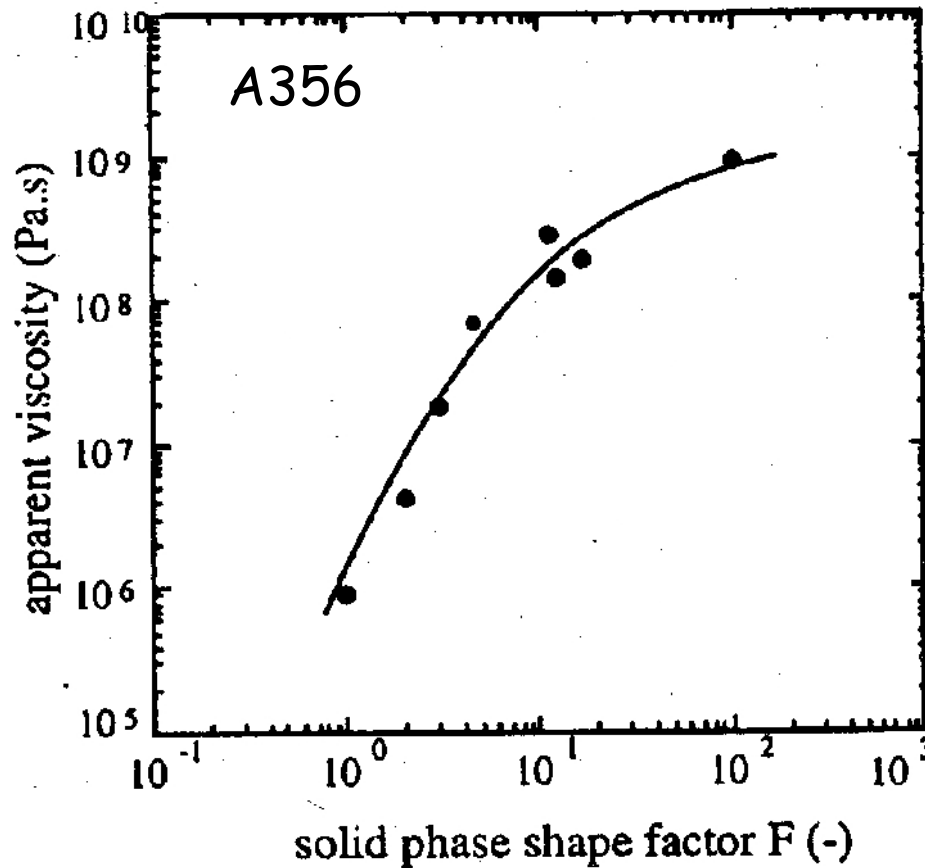
t_u = time required to
increase the shear
rate to its max. value

Effect of shape factor

$$F = 1/6\pi f_s \cdot (S_v^2/N_A)$$

Usual definition
of shape factor:

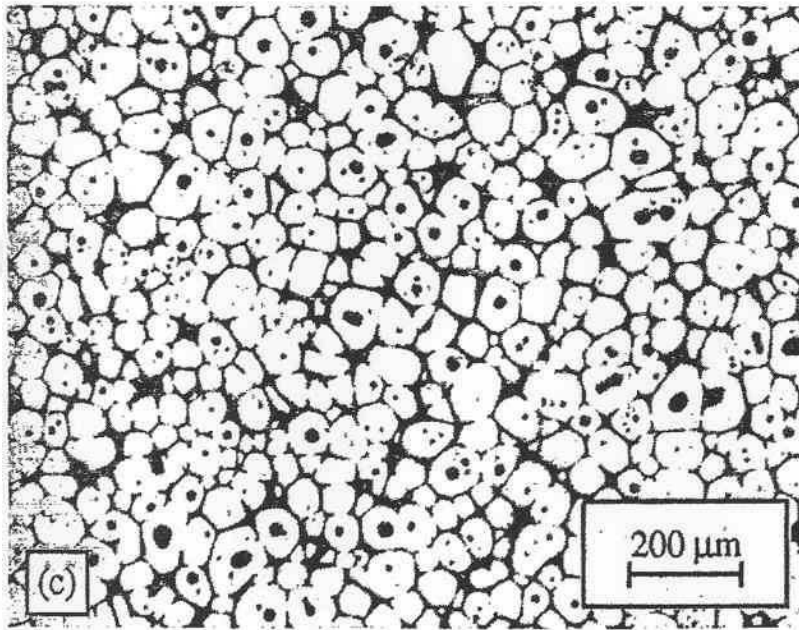
$$F = 4A/P^2$$



Effect of entrapped liquid

Semi-solid structures obtained by partial remelting

A357 alloy, 30s at 580°C



Liquid entrapped inside
the solid phase which does
not participate to the
deformation

Apparent solid fraction larger
than the real one

Effect of solid connectivity

Solid connectivity defined by the contiguity parameter

$$C_s = 2A_{ss}/(2A_{ss} + A_{sl})$$

A_{ss} = contact area between
solid particles

A_{sl} = interface area between
solid and liquid

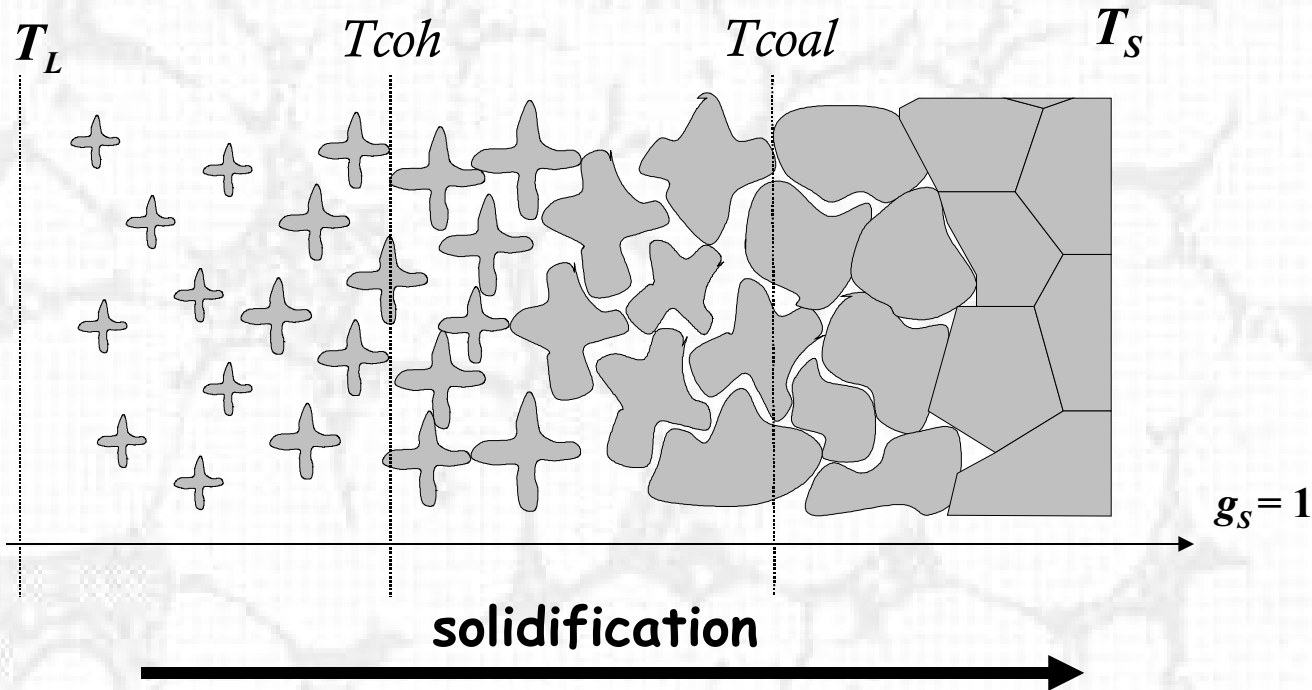
$$\text{Contiguity volume} = C_s \cdot f_s$$

For homogeneous deformation under low stresses (AA 6082)

$$C_s \cdot f_s < 0.30$$

Gullo, Steinhoff, Uggowitzer
S2P06, Torino, 2000

Phenomenology of the behaviour of dendritic structures



Between T_L and T_{coh} : solid dendrites are free to move

→ Similar behaviour as globular structures at low f_s

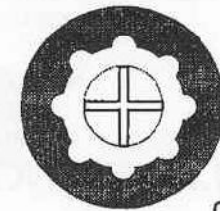
→ Low viscosity

Beyond T_{coh} : dendrites start to interact

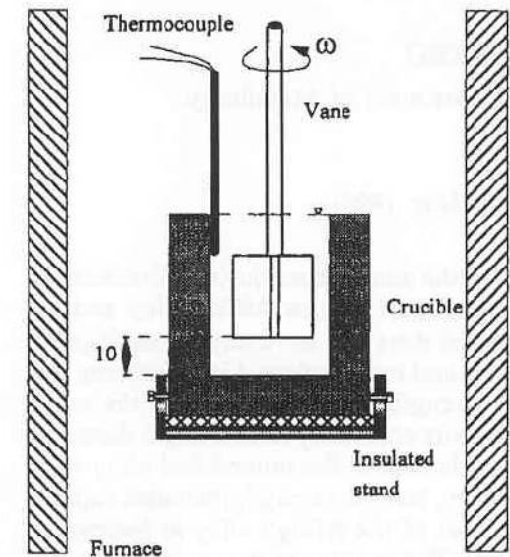
→ Shear strength becomes non negligible

Ex: shear strength measured with a vane rheometer

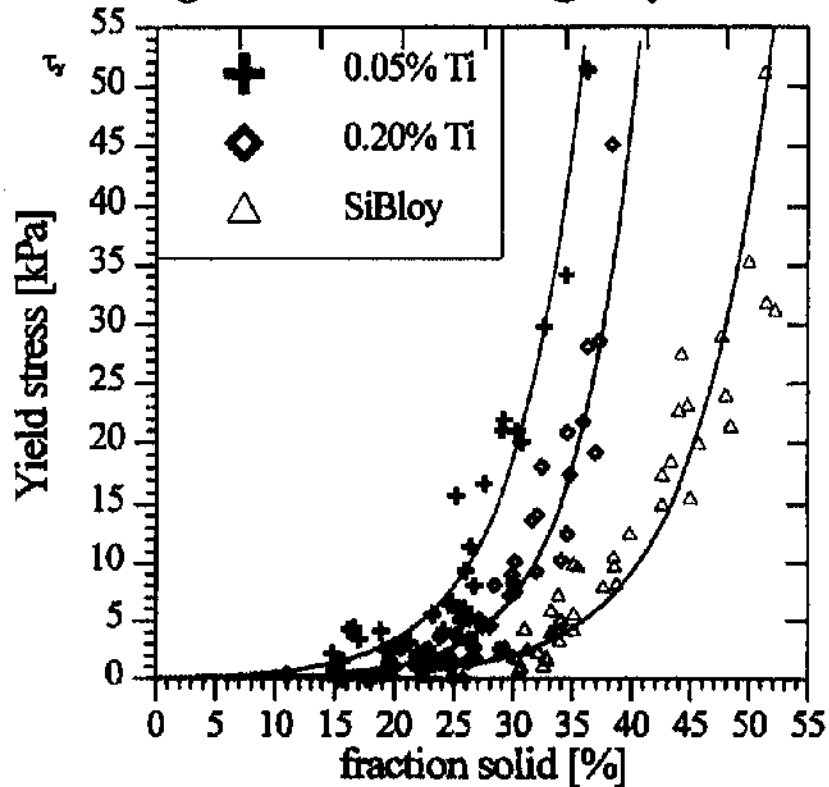
A.K. Dahle, L. Arnberg
Acta Mater. 1997



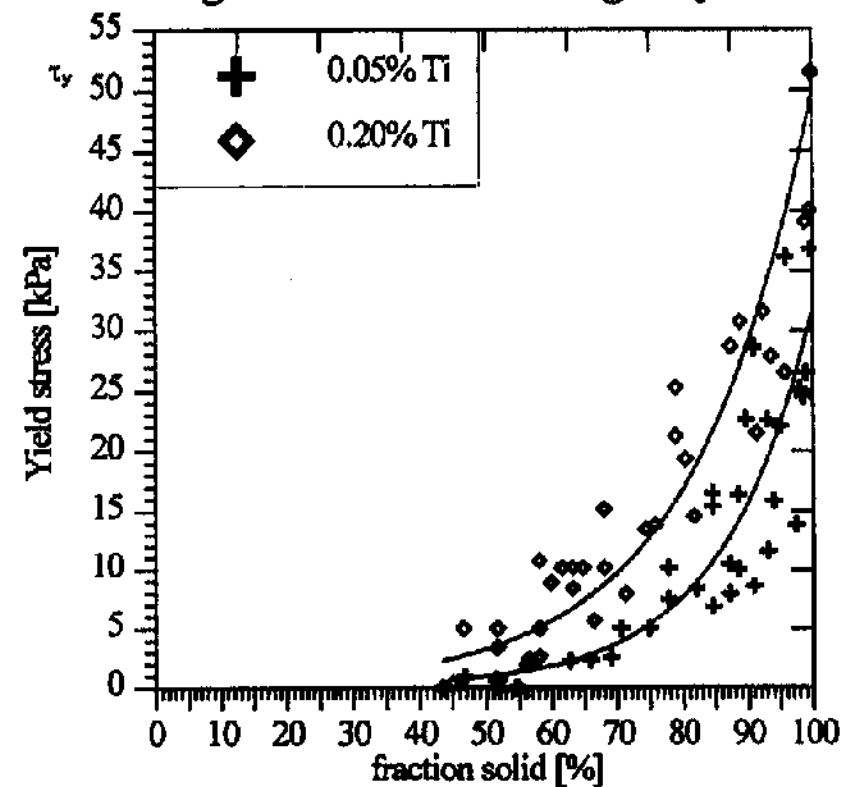
Cross-section



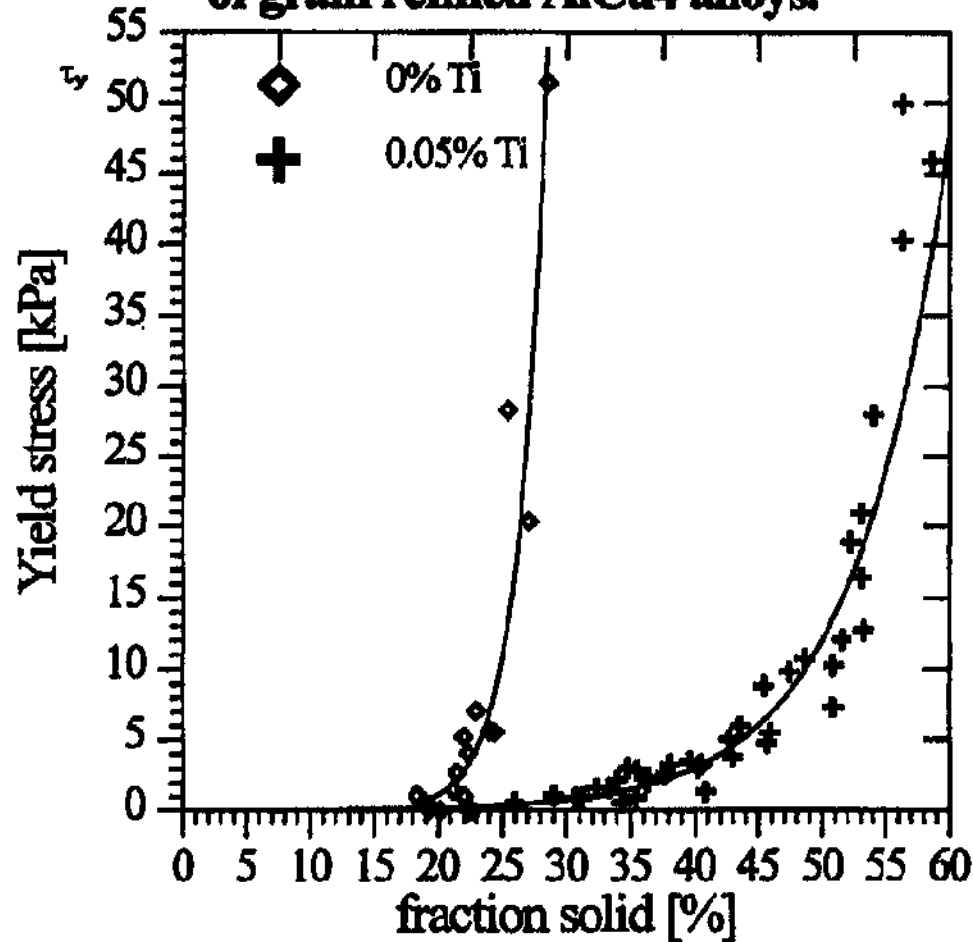
(a) **Strength development during solidification of grain refined AlSi7Mg alloys.**



(b) **Strength development during solidification of grain refined AlSi11Mg alloys.**



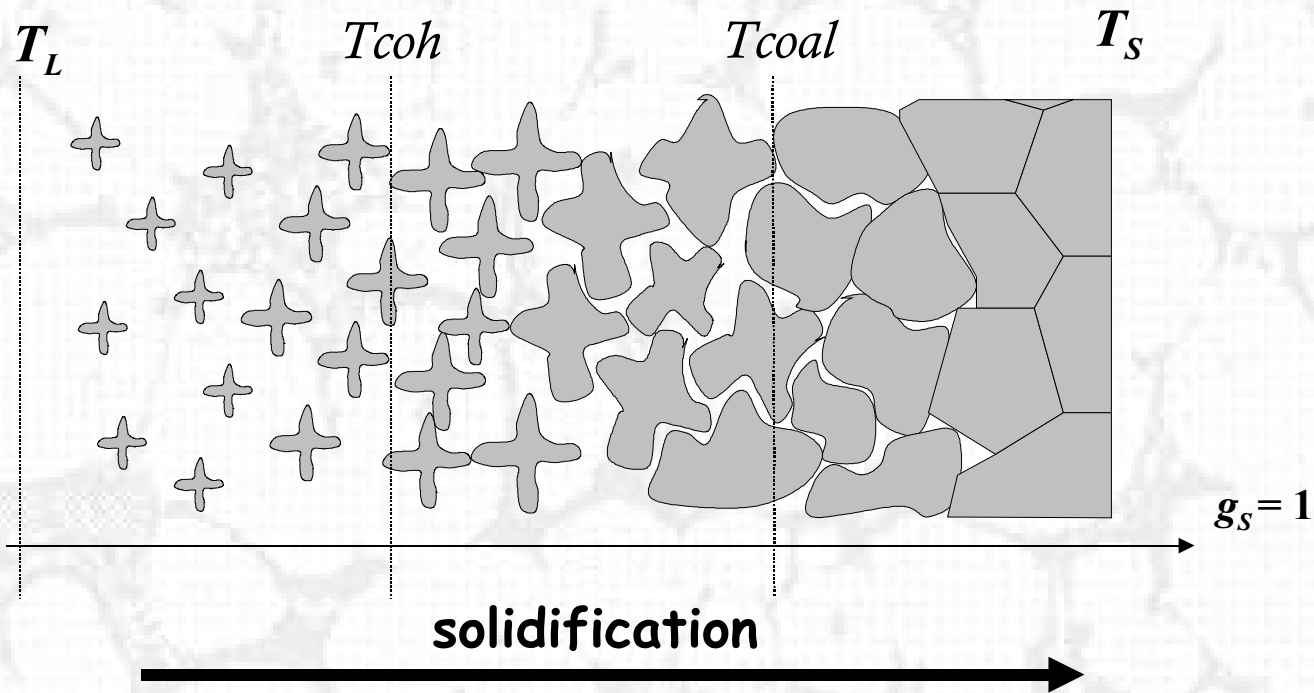
(c) **Strength development during solidification of grain refined AlCu4 alloys.**



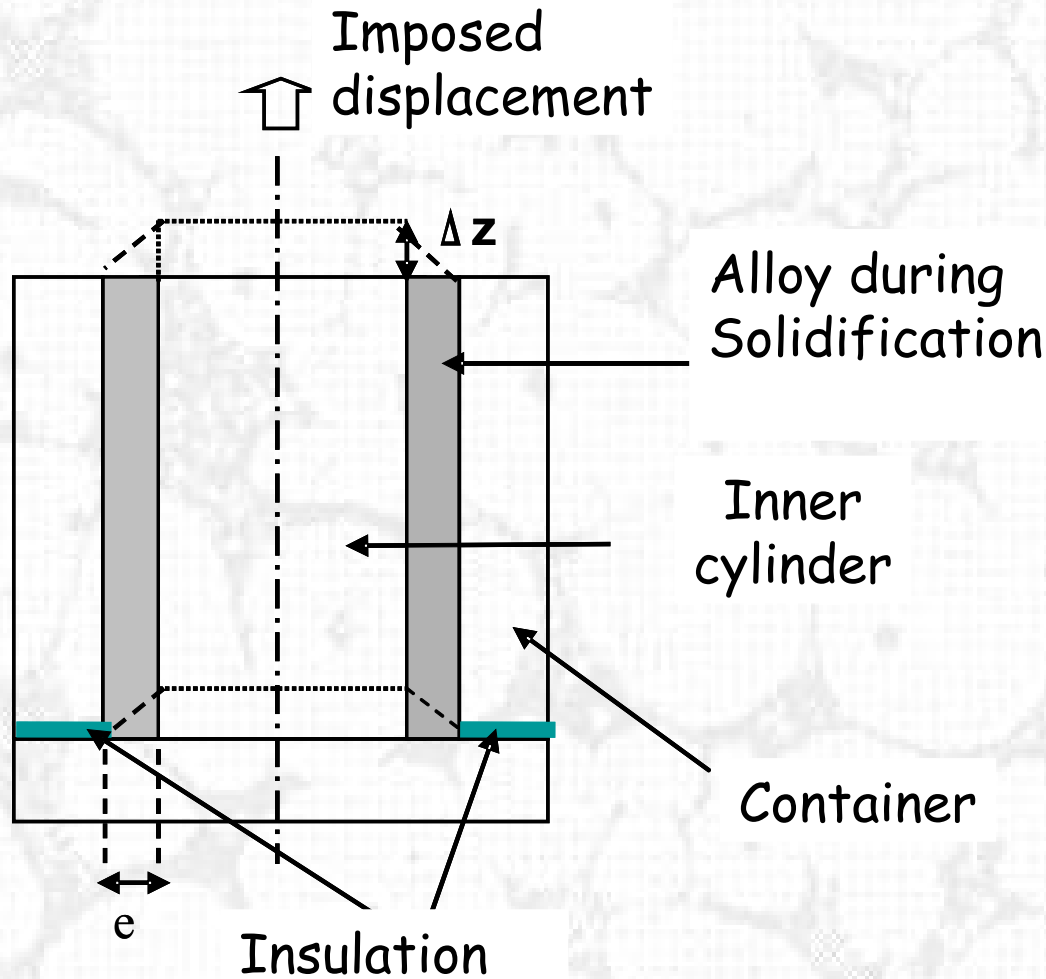
- $f_{scoh} \sim 15$ to 20 % for dendritic structures

- grain refinement increases f_{scoh}

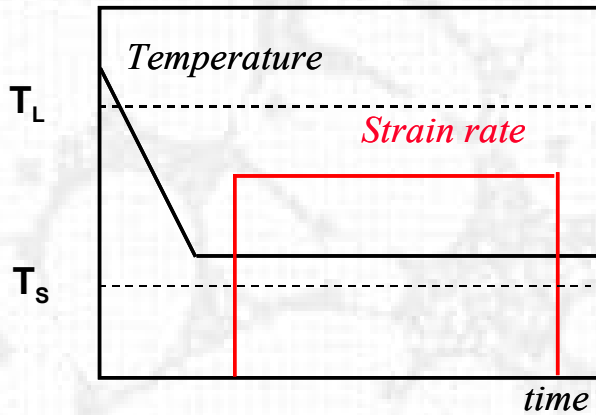
➡ Around T_{coal} : tensile stresses become important but liquid films are still present



Shear deformation

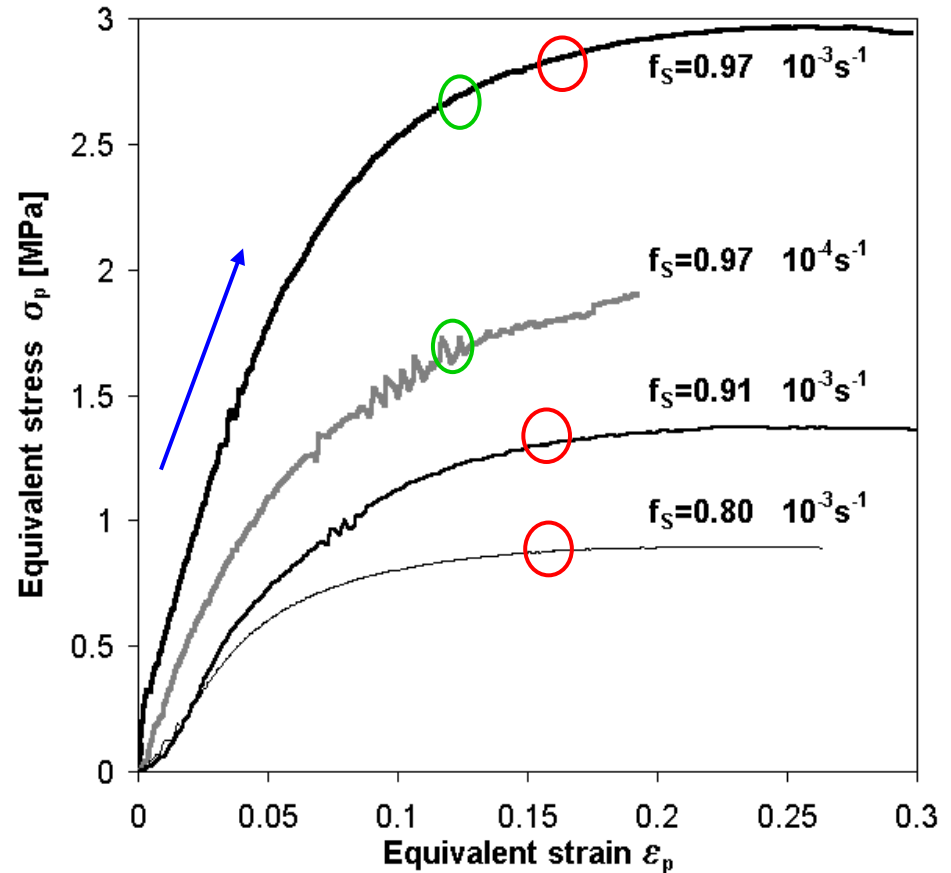


Isothermal tests after partial solidification

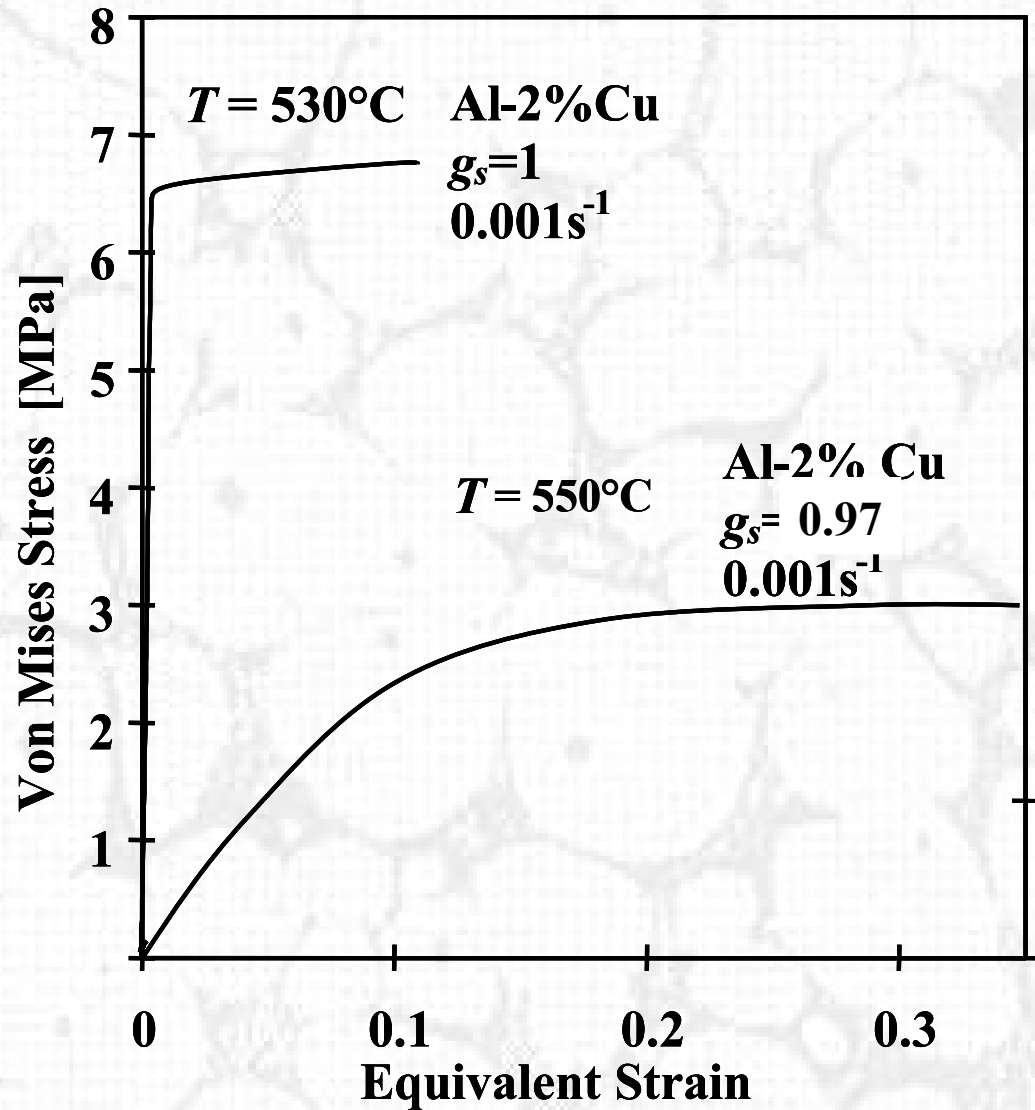


- **Effect of solid fraction**
- **Effect of shear rate**
- **Effect of strain**

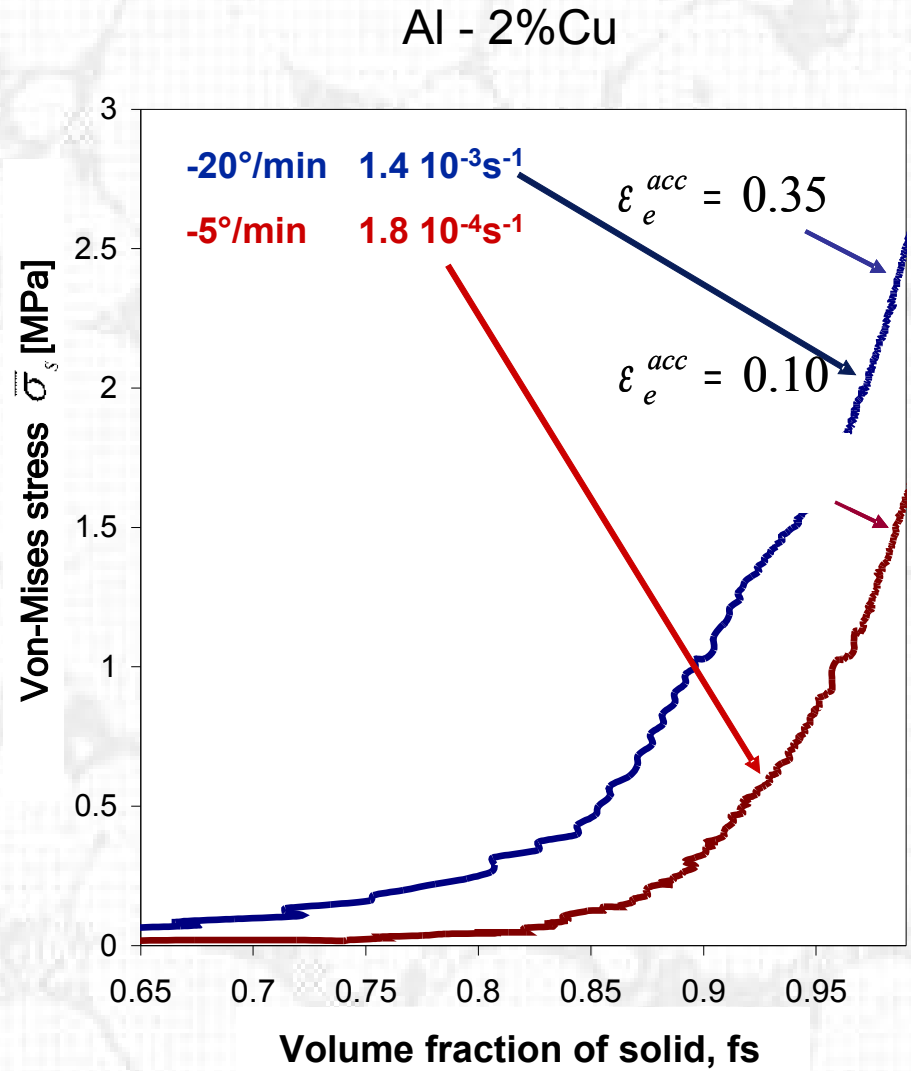
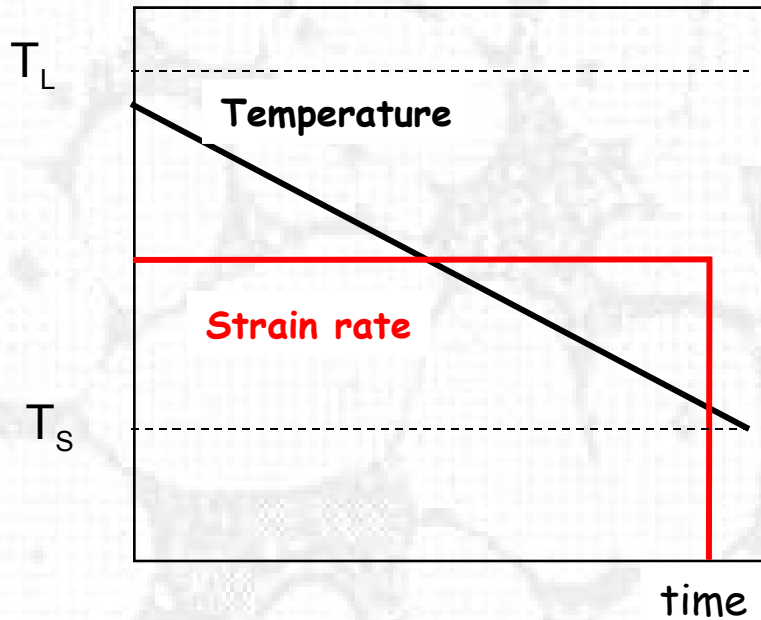
Al-2%Cu



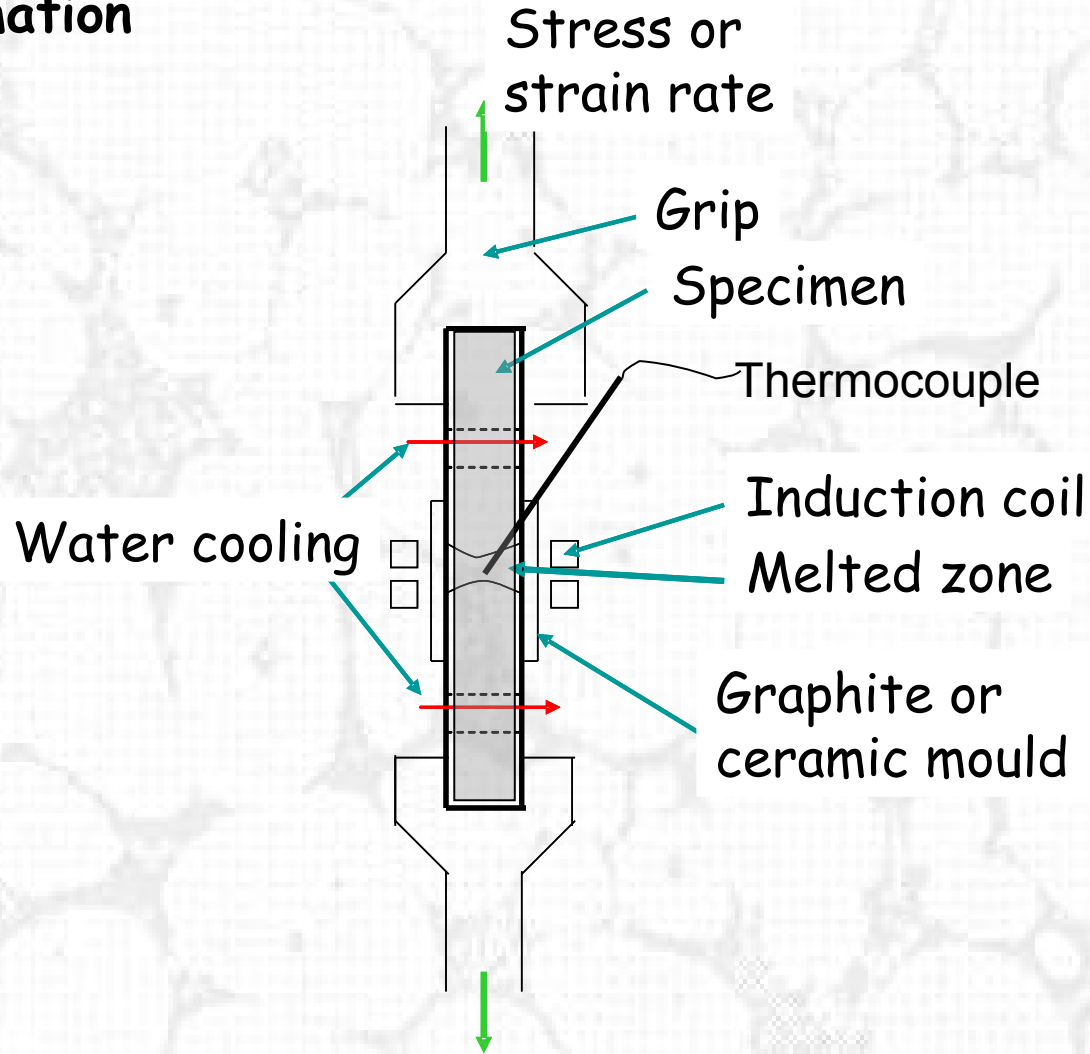
Comparison with the
fully solid alloy



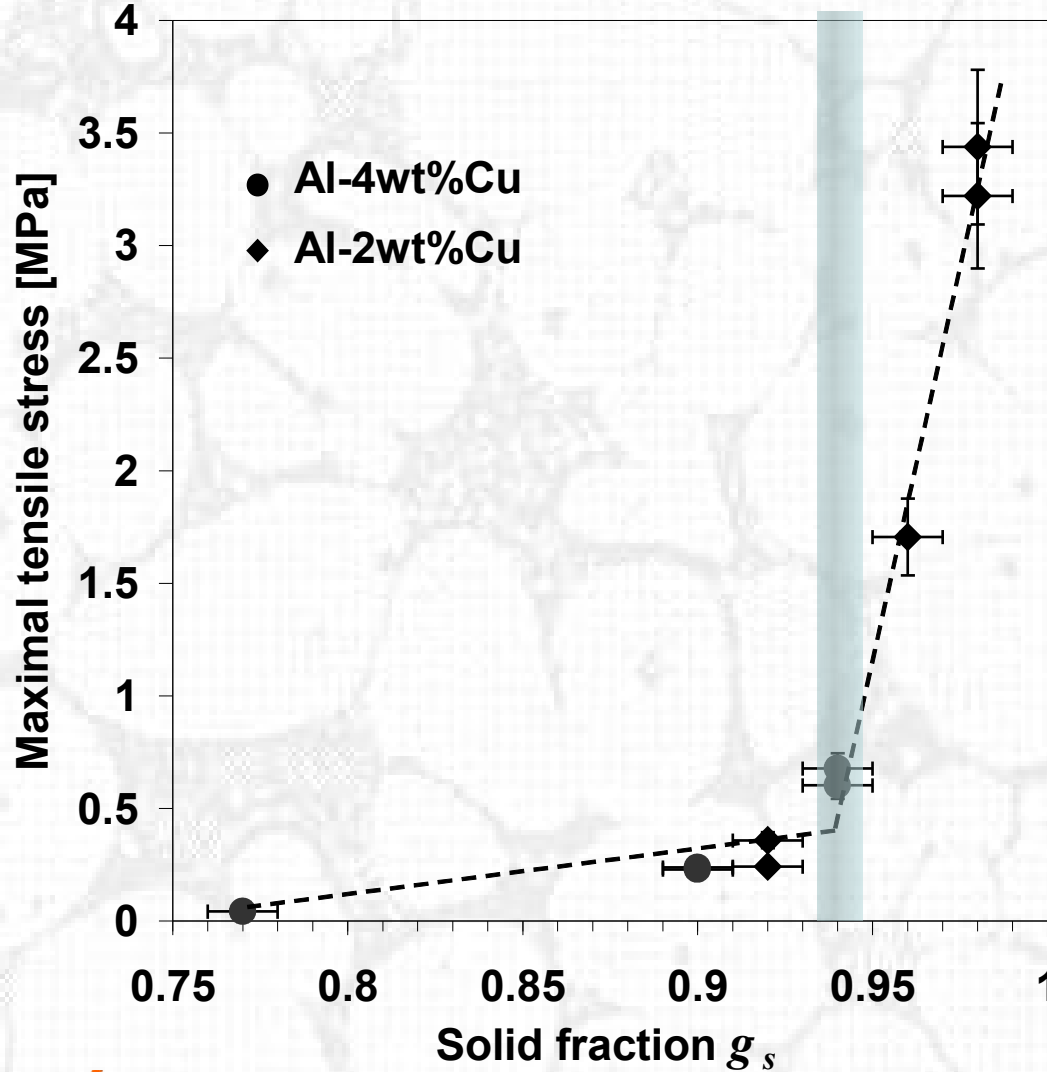
Tests during solidification



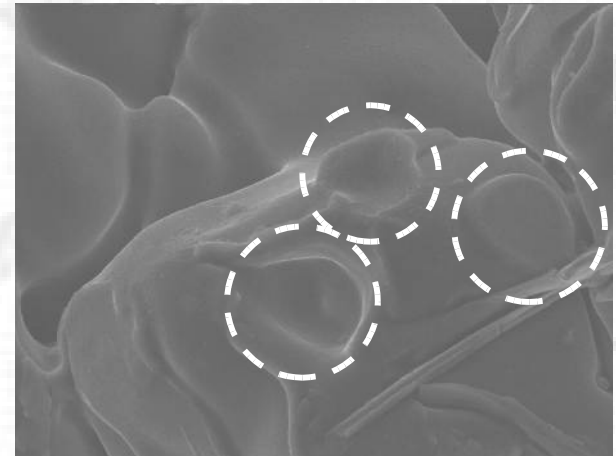
Tensile deformation



Coalescence



$g_s = 0.96$



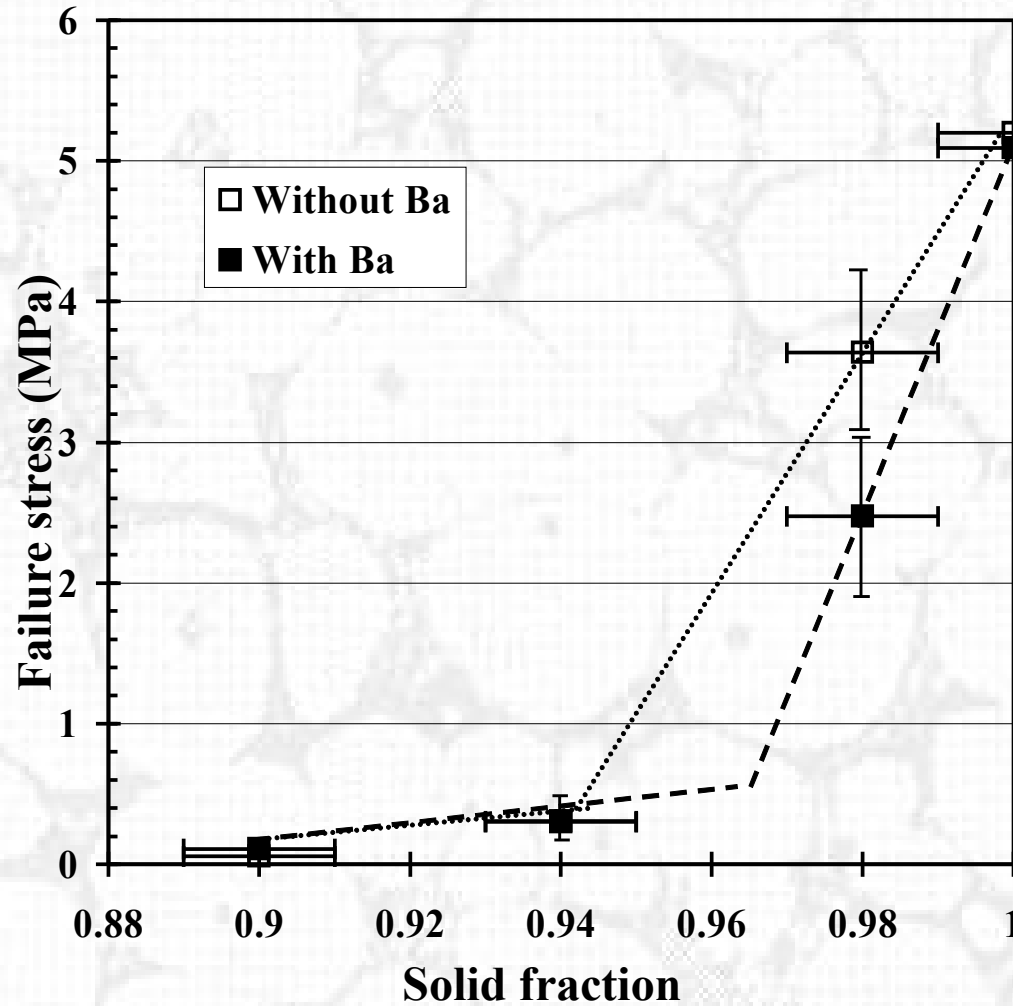
Ductile fracture of
solid bridges
between dendrites

Al-4%Cu

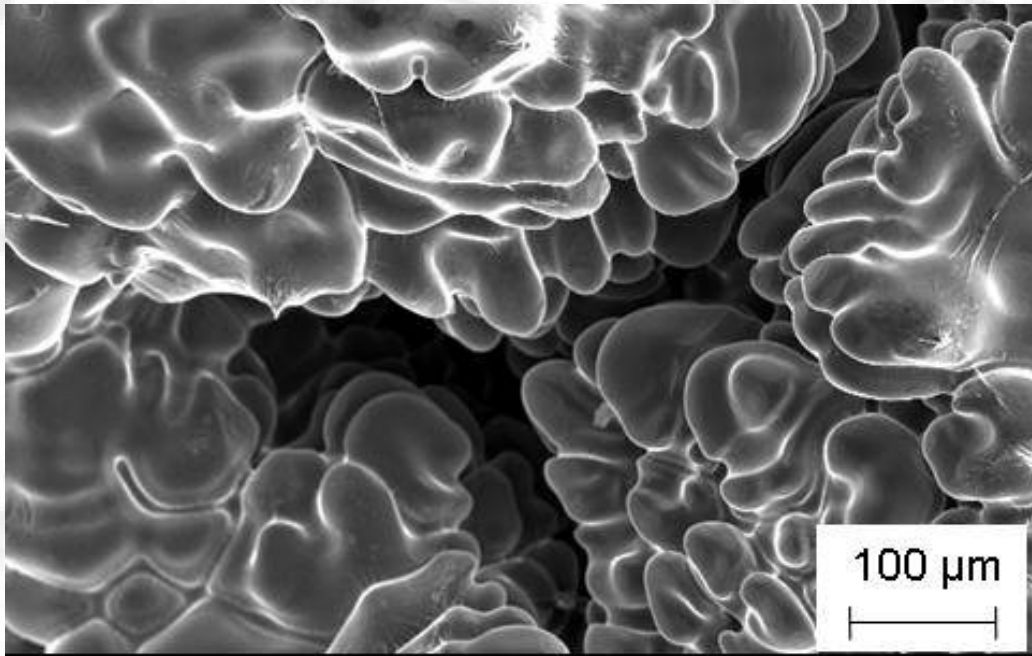
Effect of Ba
addition
(300 ppm)



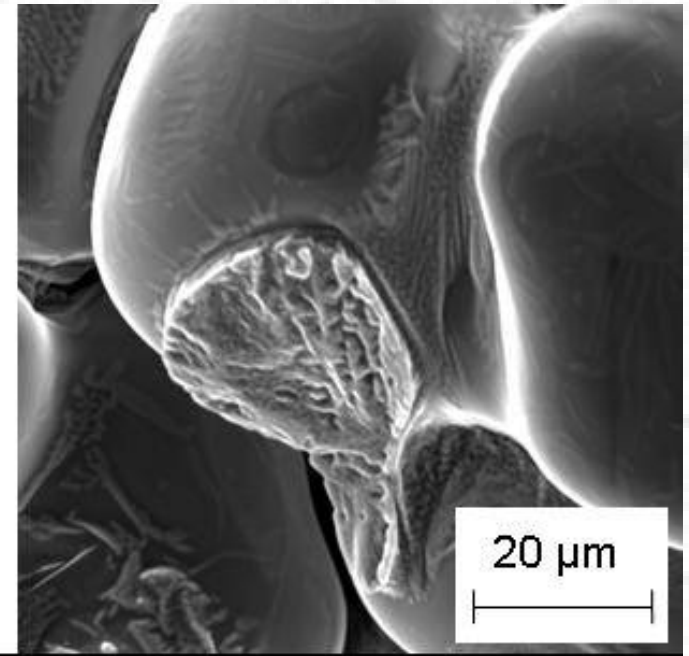
Coalescence
is delayed because
Ba lowers γ_{sl}



Fracture surfaces

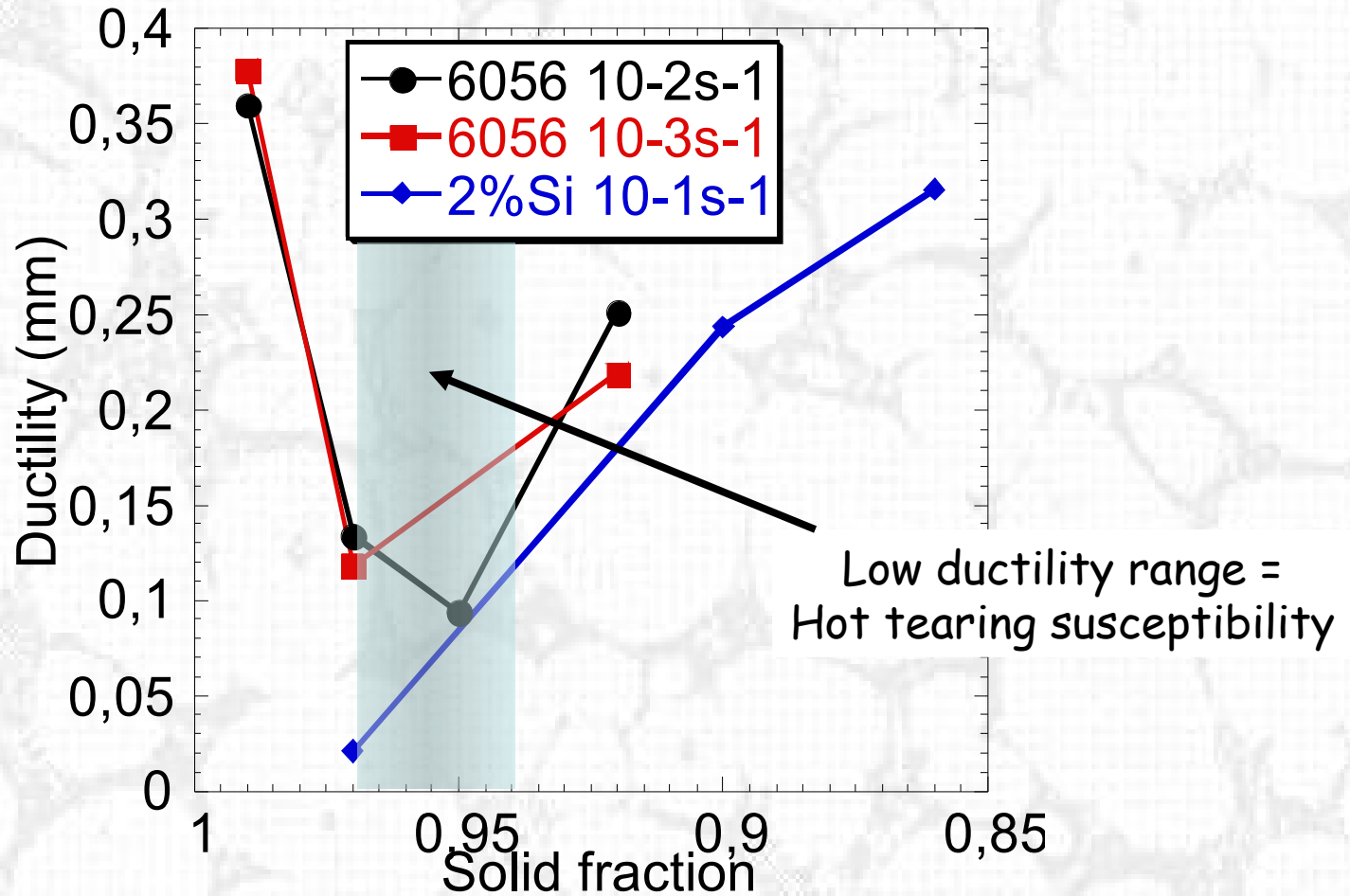


$$f_s = 0.90$$



$$f_s = 0.98$$

Other results in terms of ductility



Modelling

Suspension models

- Very low solid fractions: Einstein law

$$\eta = \eta_L (1 + 2.5 f_s)$$

- Higher solid fractions: interaction between solid globules

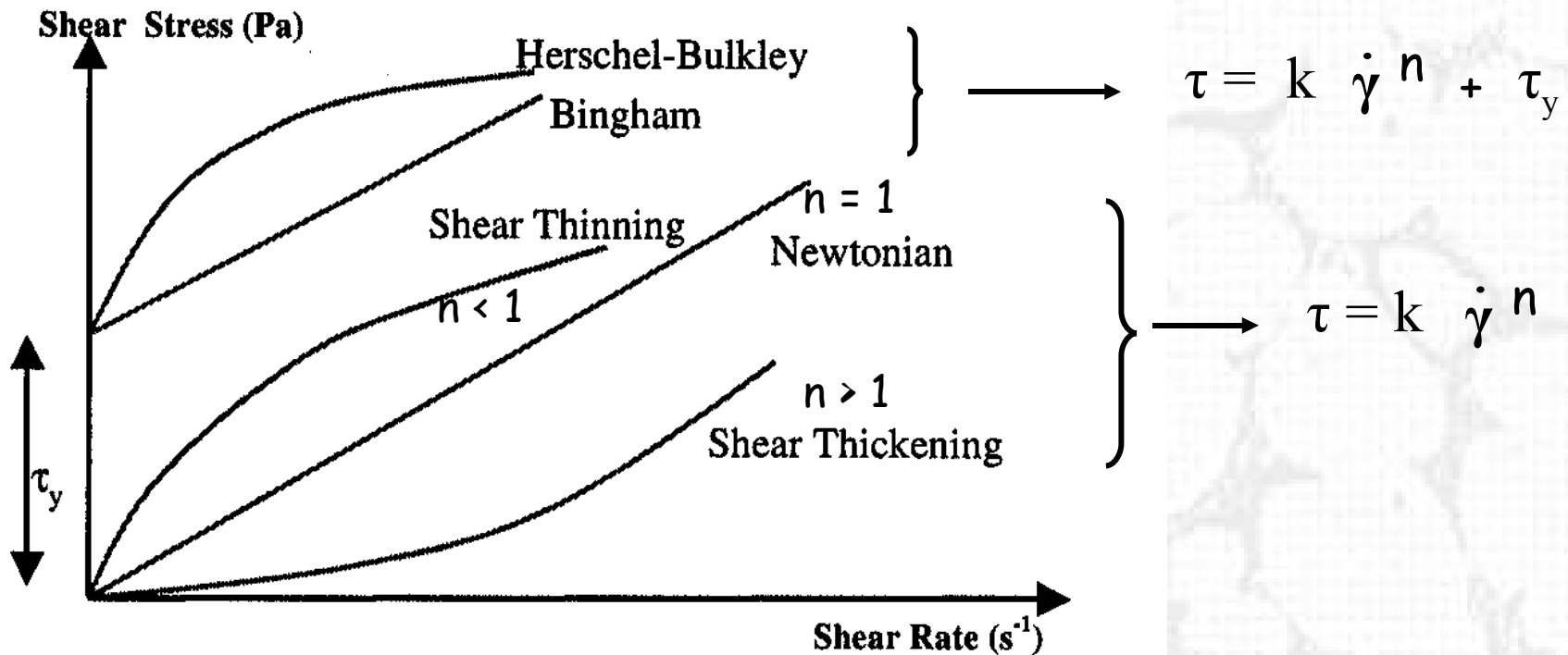
$$\eta = \eta_L \left(1 - \frac{\Phi_{\text{eff}}}{\Phi_M}\right)^{-2.5} \Phi_M$$

Krieger & Dougherty eq.
Trans. Soc. Rheol. 1959

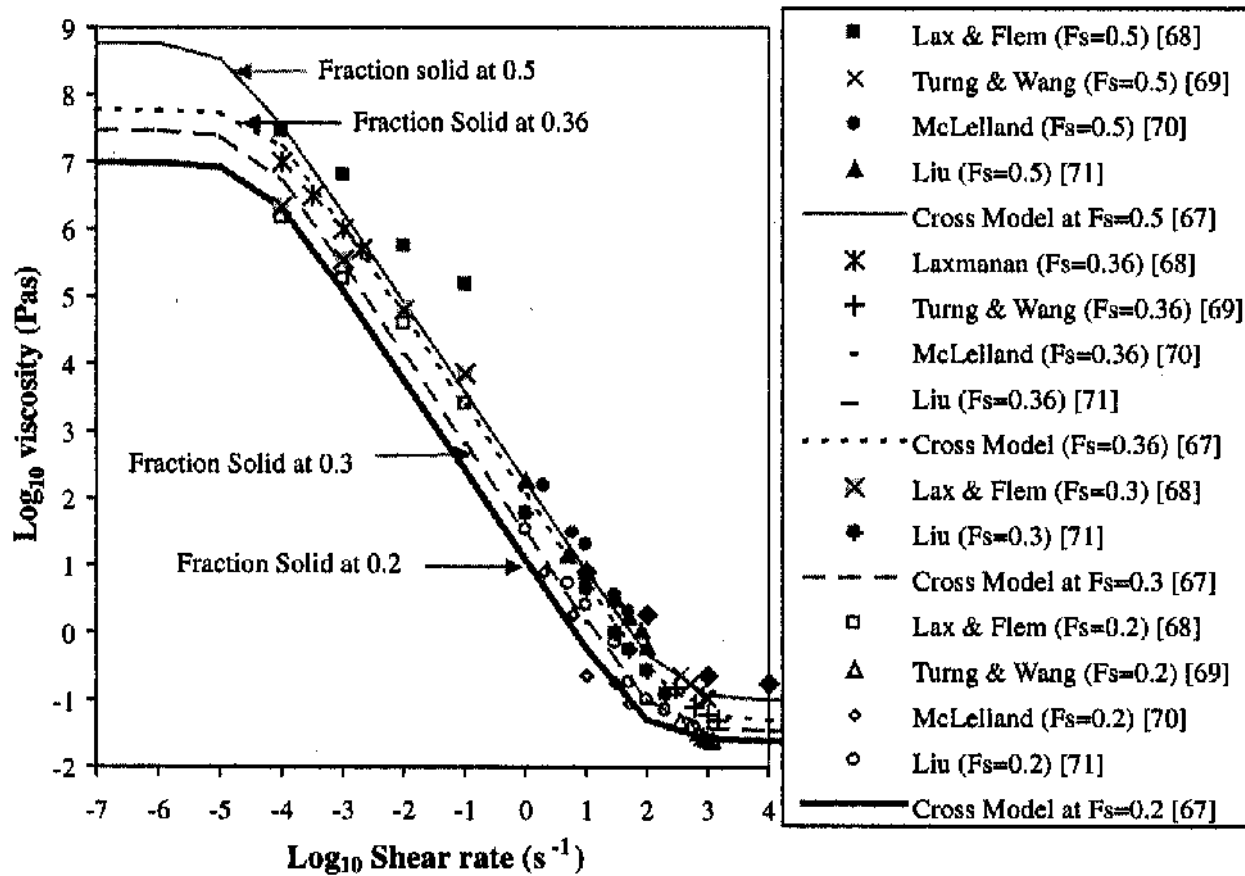
Φ_{eff} = effective solid fraction taking into account
entrapped liquid

Φ_M = maximum packing fraction of the solid

Influence of shear rate



Cross model
$$\eta = \eta_{\infty} + \left[\frac{\eta_0 - \eta_{\infty}}{1 + k\dot{\gamma}^n} \right]$$



Models incorporating a structural parameter

$$\eta = \eta (f_s, \dot{\gamma}, \lambda)$$

λ = structural parameter

1 for a completely built structure

0 for a completely broken down structure

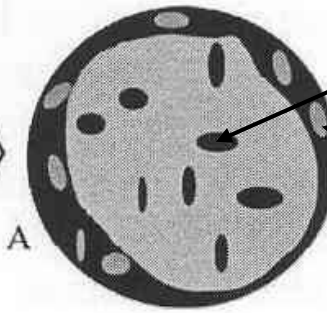
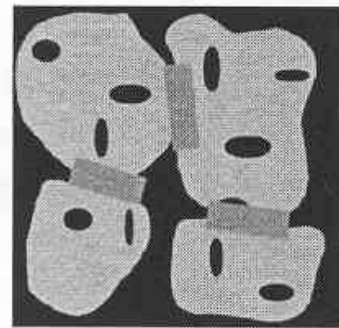
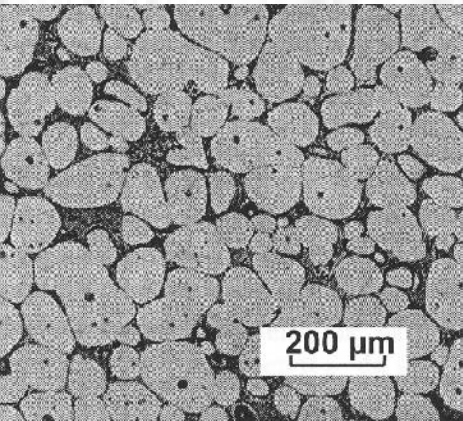
$$\frac{d\lambda}{dt} = a(1 - \lambda)^b - c\lambda\dot{\gamma}^d$$

Build-up

Breakdown

Micro-macro modelling approach

V. Favier & al.
Int. J. Forming
Processes, 2004



Interglobular
liquid

Solid
contacts



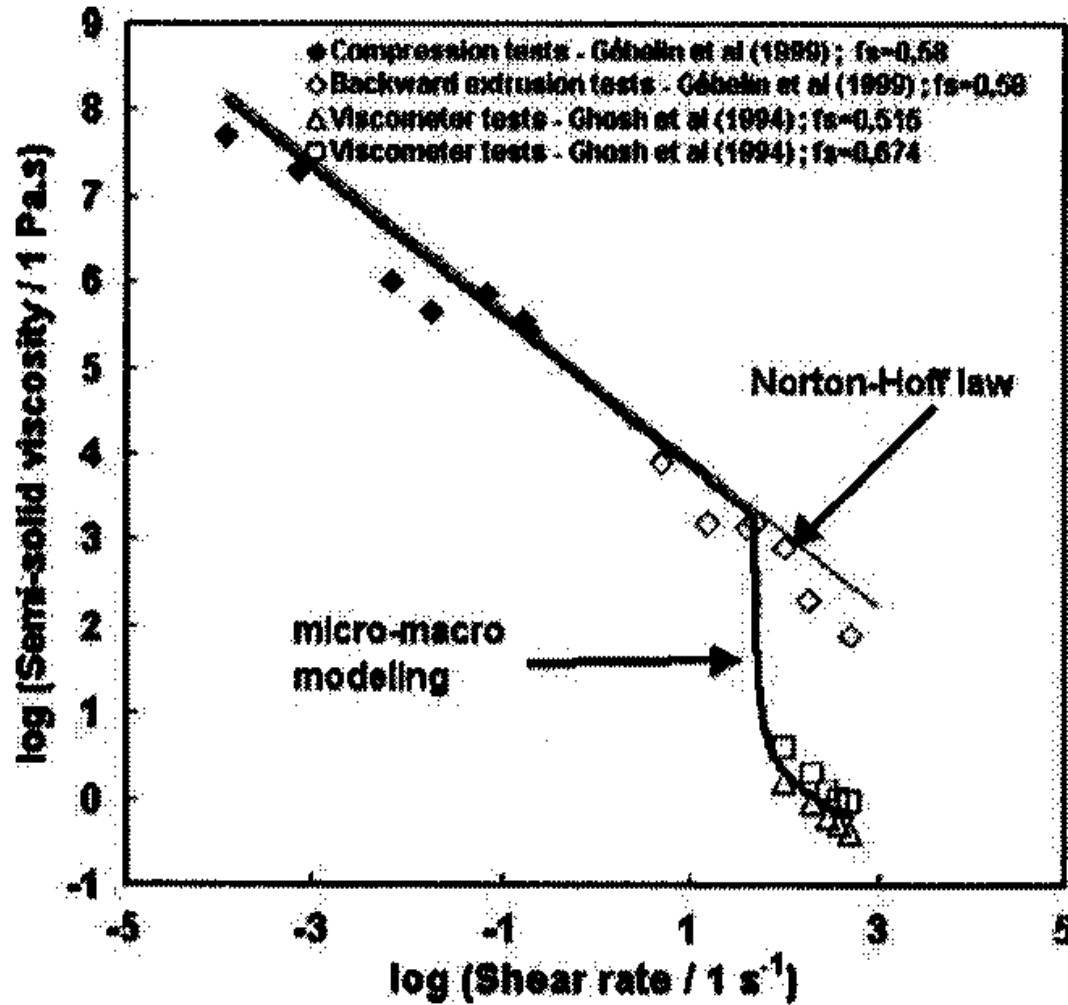
B

inclusion

coating
(active zone)

fs_A depends on
shear rate and
solid fraction

fs_A



Two-phase models

Basic assumptions :

- partition of stress into two parts:
 - deviatoric part of the macroscopic stress assumed to be carried exclusively by the skeleton of solid grains
 - hydrostatic part, which is partially carried by the solid and partially by the liquid phase.

$$\mathbf{S}_{EFF} = \mathbf{S} - \delta p_L \mathbf{1}$$

or

$$\mathbf{S}_{EFF} = \mathbf{S} - (1 - f_S) p_L \mathbf{1}$$

- solid skeleton considered as a porous medium
- liquid flow described by Darcy's law

Solid skeleton

$$\mathbf{D}^p = \frac{\partial \Phi}{\partial \Sigma_{EFF}}$$

$$\Phi = \hat{\Phi}(\sigma_e, \sigma_h)$$

$$\left\{ \begin{array}{l} \sigma_e = \sqrt{3/2 \Sigma'_{EFF} \cdot \Sigma'_{EFF}} \\ \Sigma'_{EFF} = \Sigma_{EFF} - \sigma_h \mathbf{1} \\ \sigma_h = (\text{tr} \Sigma_{EFF}) / 3 \end{array} \right.$$

For the dense solid

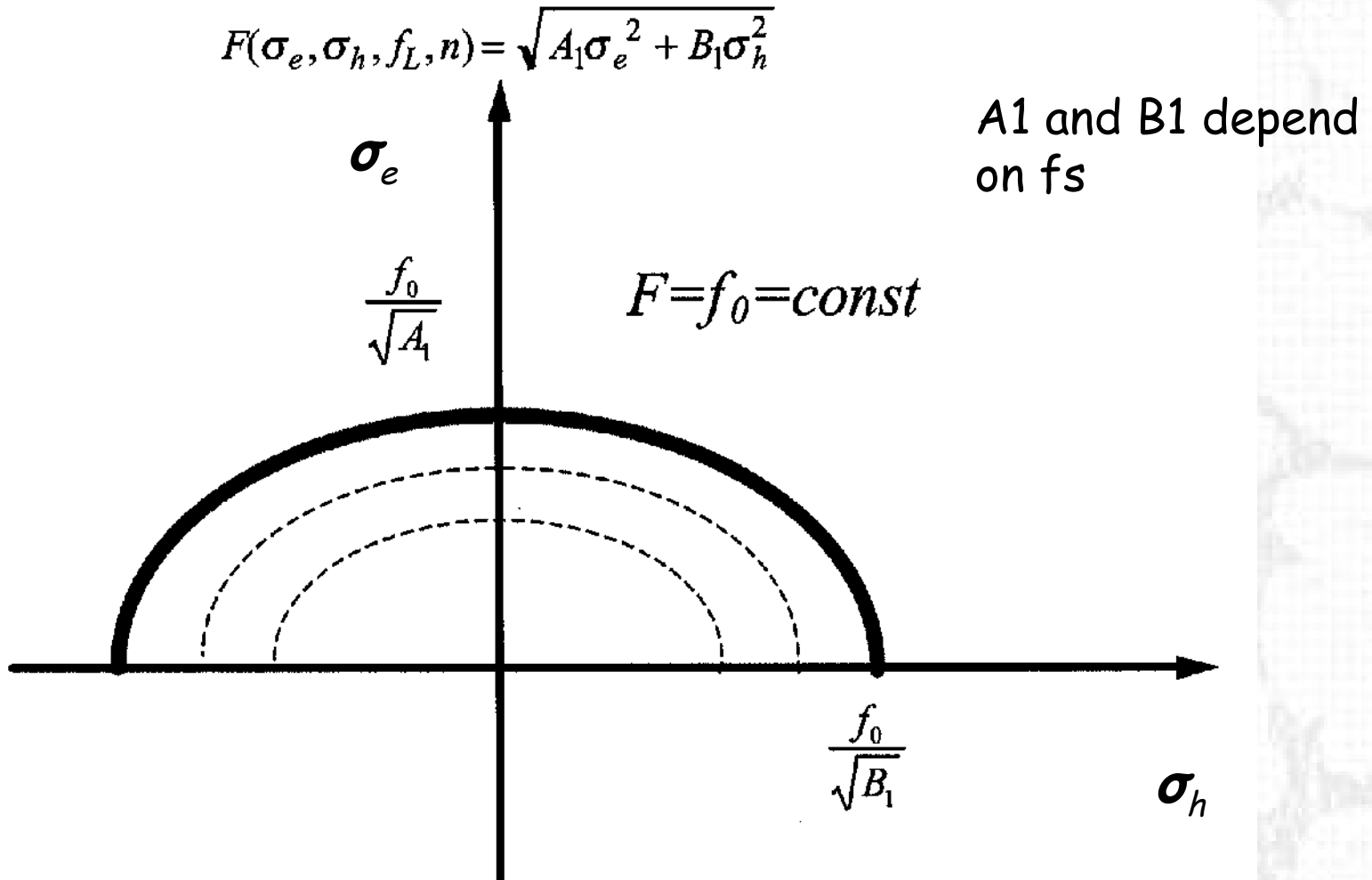
$$\Phi_d = \frac{\dot{\epsilon}_0 \sigma_0}{n+1} \left(\frac{\sigma_e}{\sigma_0} \right)^{n+1}$$

For the porous solid

$$\Phi = \frac{\dot{\epsilon}_0}{(n+1)\sigma_0^n} F(\sigma_e, \sigma_h, f_L, c, n, \dots)^{n+1}$$

$$\Sigma_{EFF} \cdot \mathbf{D}^p = (1 - f_L) \sigma_{eq} \dot{\epsilon}_{eq} \quad \text{where } \dot{\epsilon}_{eq} = \dot{\epsilon}_0 \left(\sigma_{eq} / \sigma_0 \right)^n$$

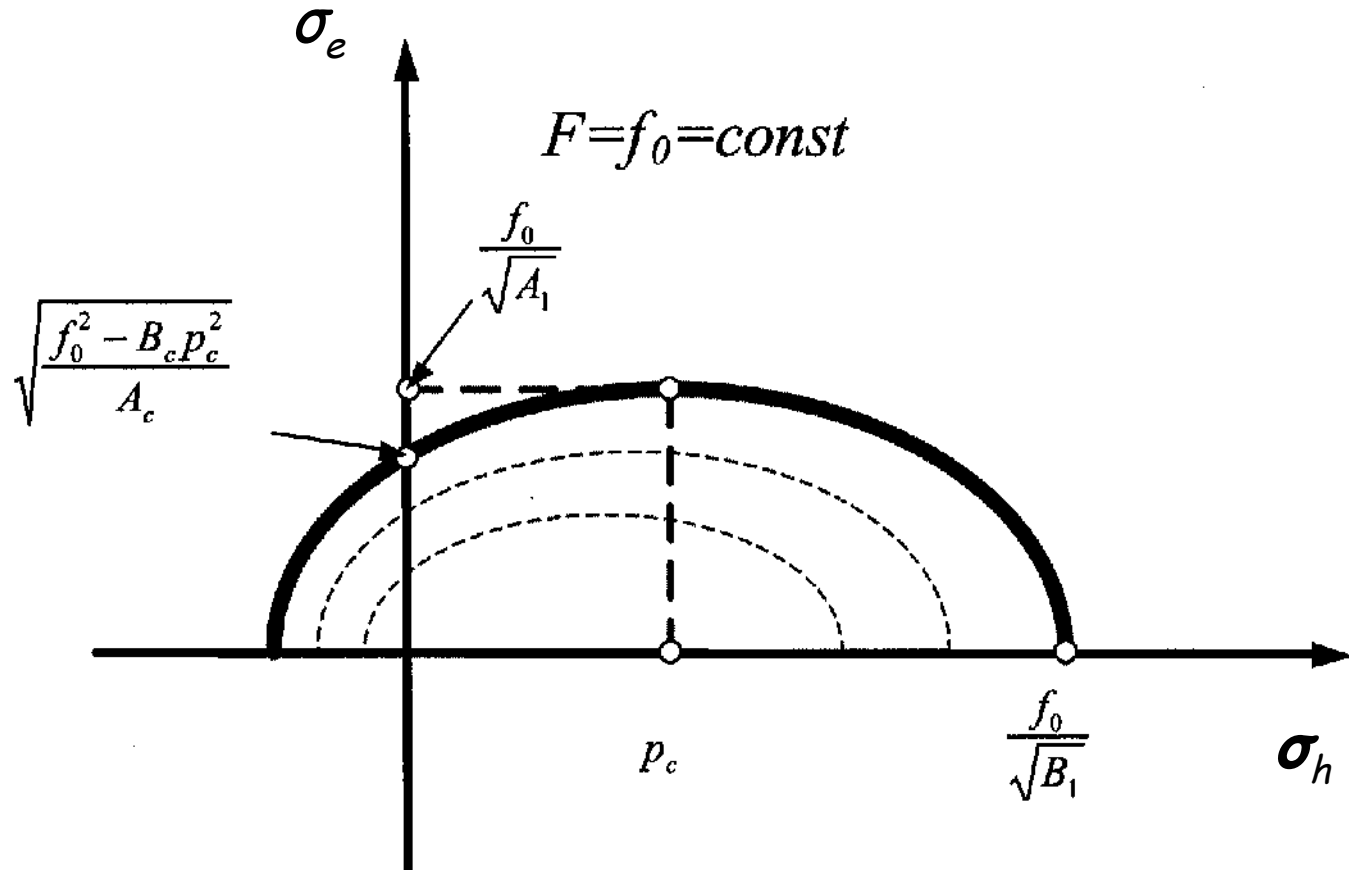
Centered ellipse



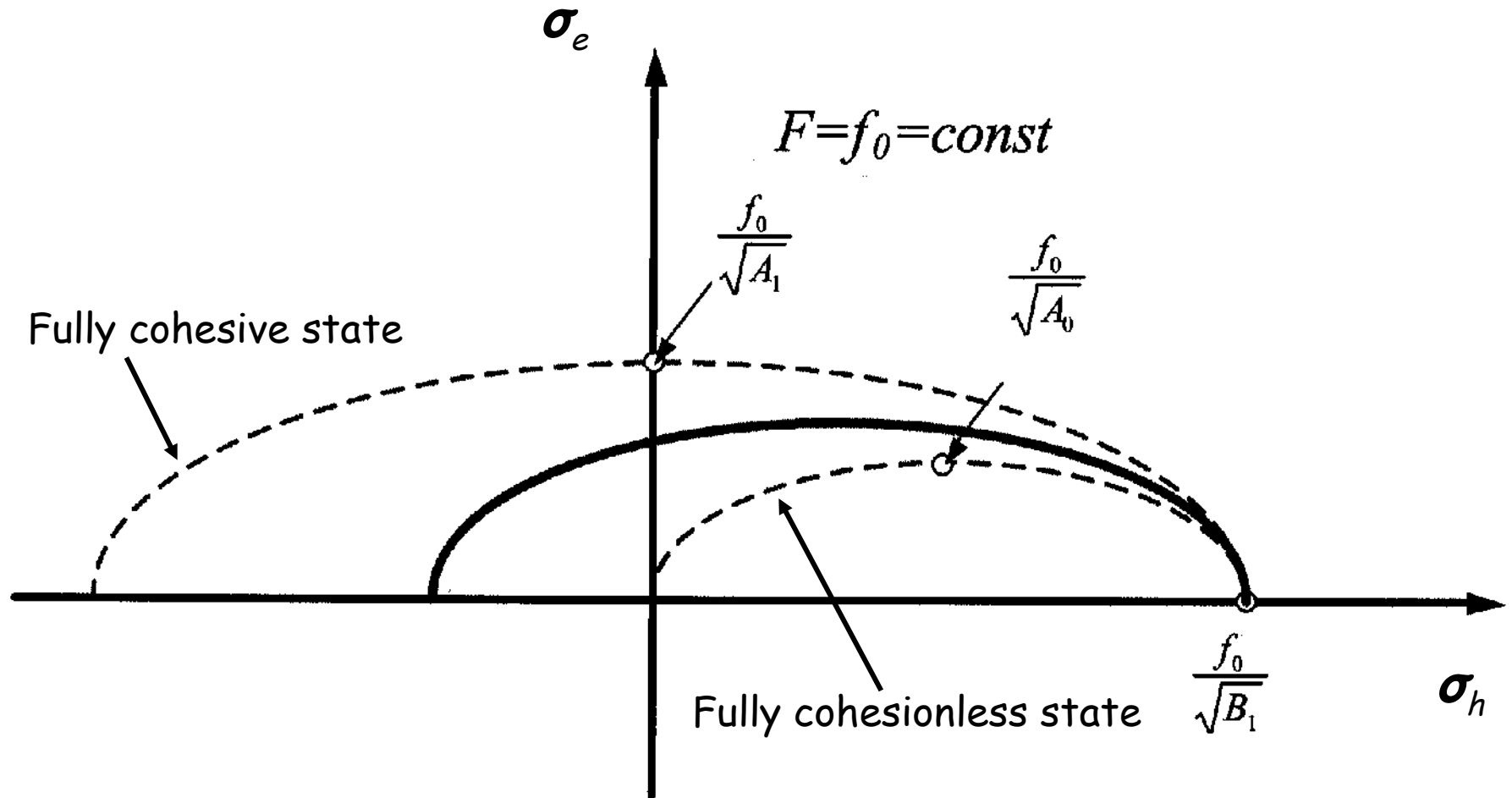
Non centered ellipse

$$F(\sigma_e, \sigma_h, f_L) = \sqrt{A_c \sigma_e^2 + B_c (\sigma_h + p_c)^2}$$

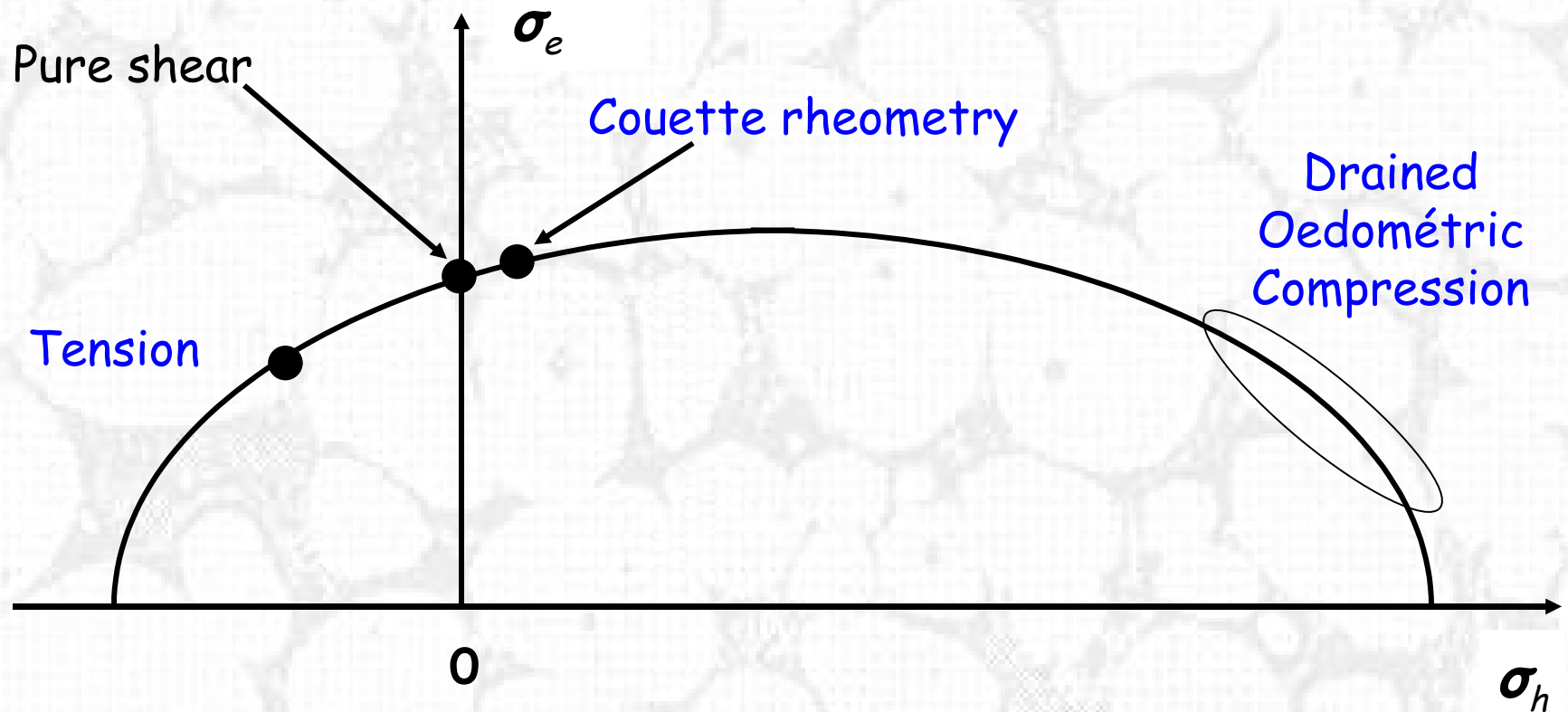
Tension \neq compression



Thixotropic non centered ellipse



Experiments to be carried for identification



Liquid flow

Darcy's law

$$f_L \mathbf{v}_L = -\frac{\mathbf{K}}{\mu} \cdot (\nabla p_L - \rho_L \mathbf{g})$$

\mathbf{K} : permeability tensor (anisotropic in the general case)

Isotropic permeability:

$$K = \frac{d_m^2}{180} \frac{f_L^3}{(1 - f_L^2)}$$

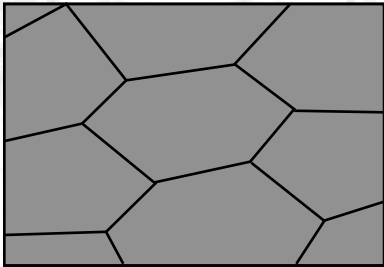
Carman-Kozeny

d_m = average grain size for equiaxed microstructures

Modelling at very high solid fractions

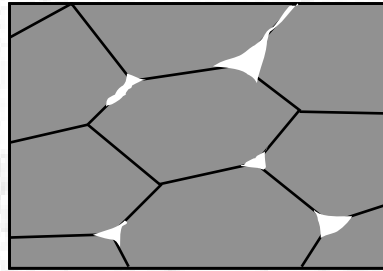
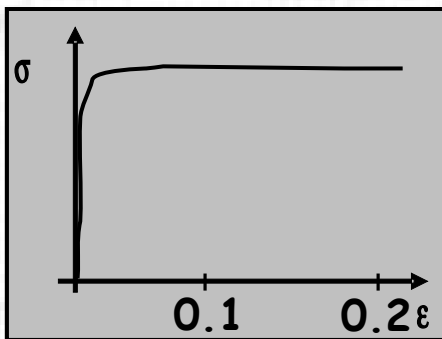
- Between T_{coal} and T_s : liquid flow no longer possible (liquid pockets)
 - ⇒ viscoplastic deformation of a porous solid saturated with liquid

However, presence of liquid induces a partial cohesion of the solid which is evolving during deformation



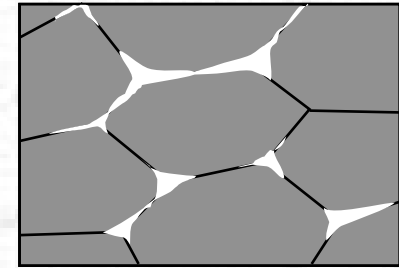
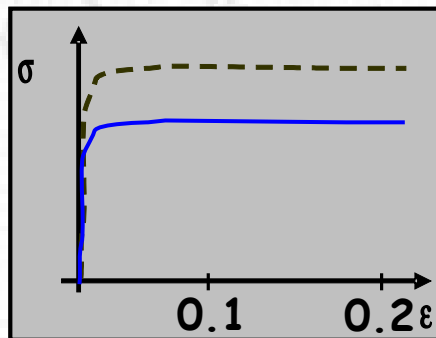
$$g_s = 1$$

Solid alloy at
high
temperature



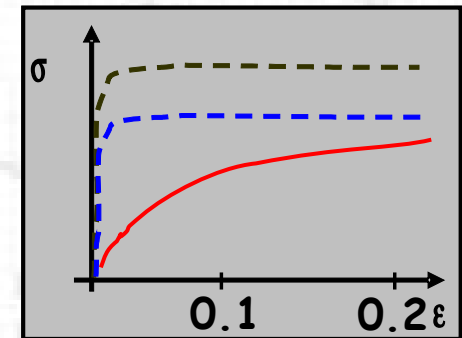
$$g_s < 1$$

Porous alloy
saturated
with liquid



$$g_s < 1, C < 1$$

Alloy with
Partial
cohesion



$$\dot{\boldsymbol{\varepsilon}}_s^p = \frac{\dot{\boldsymbol{\varepsilon}}_0}{(C_{S_0})^n} \left\{ -\frac{A_2}{3} \bar{P}_s \mathbf{1} + \frac{3}{2} A_3 \mathbf{S}_s \right\} \left\{ A_2 \bar{P}_s^2 + A_3 \bar{\sigma}_s^2 \right\}^{\frac{n-1}{2}}$$

$$\frac{dC}{dt} = \alpha(\mathbf{g}_s, X) \left(1 - \frac{C}{C^*(\mathbf{g}_s, X)} \right) \dot{\boldsymbol{\varepsilon}}_e$$

C = solid cohesion

X = stress triaxiality

C^* = cohesion at saturation

$\alpha(\mathbf{g}_s, X)$ and $C^*(\mathbf{g}_s, X)$ must be determined experimentally

\mathbf{g}_s evolves with **solidification** and **strain**

Example: Al-2%Cu during shear

$$\alpha \left(g_s, X = 0 \right) = \alpha_0 + \alpha_1 \frac{g_s^{\frac{1}{3}}}{1 - g_s^{\frac{1}{3}}}$$

$$C^* \left(g_s, X = 0 \right) = 1 - \left(1 - g_s \right)^p$$

$$\alpha_0 = 4.45$$

$$\alpha_1 = 1.07 \cdot 10^{-2}$$

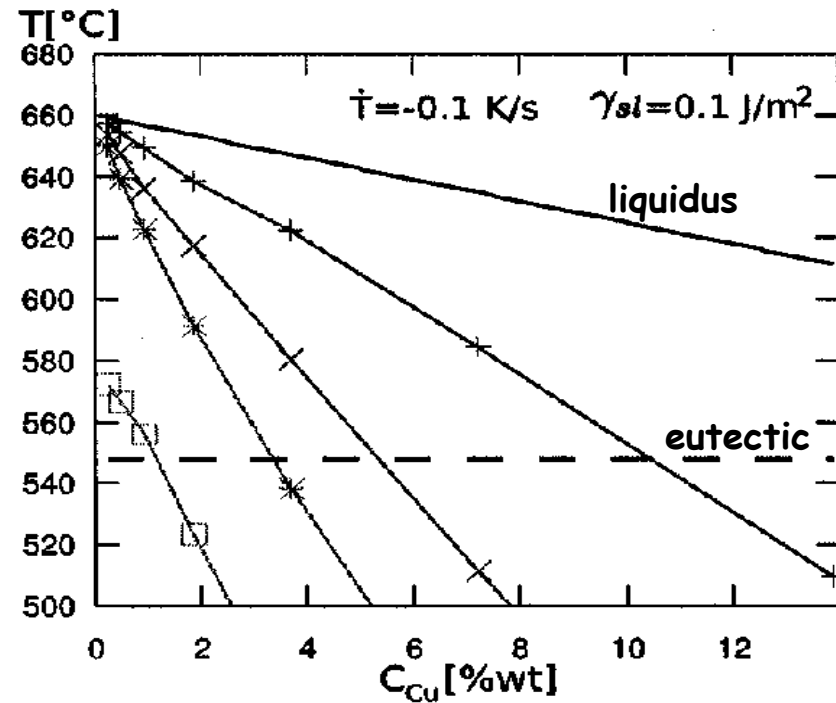
$$p = 0.11$$

Another approach = granular model for equiaxed mushy zones (2D)

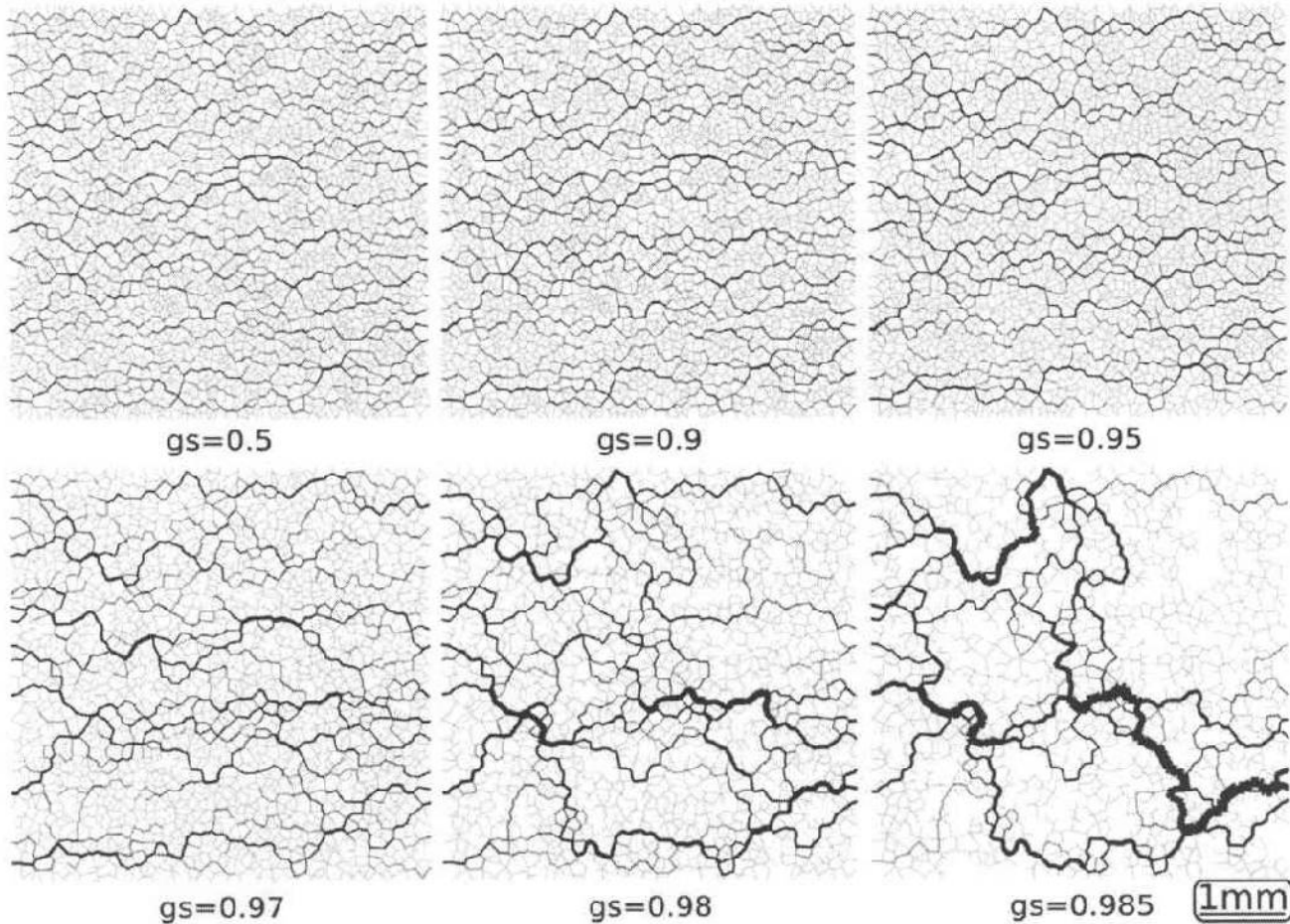
Vernede et al. Acta Mat. 2006

→ Prediction of the various solid transitions

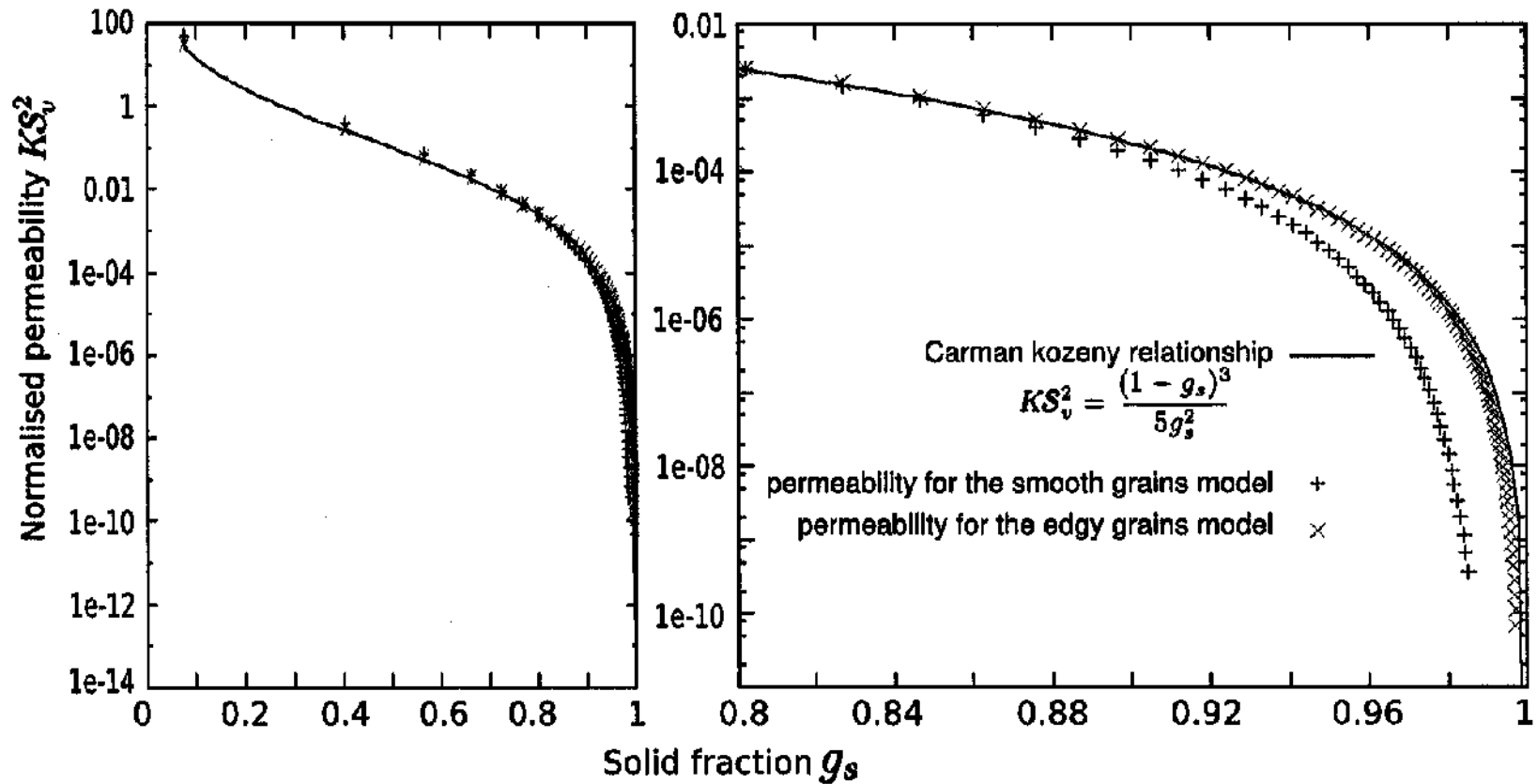
Grain contact +
Liquid isolation ×
Percolation by contact *
Percolation by bridging □



→ Analysis of liquid flow ⇒ permeability



Permeability



Conclusion

- Rheological behaviour of partial melts is complex
 - effect of strain rate
 - effect of solid fraction (suspension, f_{coh} , f_{coal})
 - effect of time and strain
 - effect of stress state

- Modelling is also necessarily complex

- Identification of models is difficult
 - Partial remelting/solidification
 - High temperature
 - Several types of tests

Acknowledgements

Researchers in INPG

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- RNMP, MINEFI, ASA project

Thank you for your attention

Questions?